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NOIDA INSTITUTE OF ENGINEERING AND TECHNOLOGY, GREATER NOIDA

(An Autonomous Institute Affiliated to AKTU, Lucknow)

M.Tech

SEM: II - THEORY EXAMINATION (2022-2023)

Subject: Real Time Operating System

Time: 3 Hours

Max. Marks: 70

General Instructions:

IMP: Verify that you have received the question paper with the correct course, code, branch etc.

1. This Question paper comprises of **three Sections -A, B, & C**. It consists of Multiple Choice Questions (MCQ's) & Subjective type questions.
2. Maximum marks for each question are indicated on right -hand side of each question.
3. Illustrate your answers with neat sketches wherever necessary.
4. Assume suitable data if necessary.
5. Preferably, write the answers in sequential order.
6. No sheet should be left blank. Any written material after a blank sheet will not be evaluated/checked.

SECTION A

15

1. Attempt all parts:-

- 1-a. Messages sent by a process have _____. (CO1) 1
- (a) fixed size
 - (b) variable size
 - (c) fixed or variable sized
 - (d) none of the mentioned
- 1-b. Where are the device drivers located in RTOS with a microkernel. (CO2) 1
- (a) In the kernel space
 - (b) In the user space
 - (c) In separately allocated space which is neither kernel space nor user space.
 - (d) None
- 1-c. _____ is the process of writing processor specific machine code in mnemonic form, converting the mnemonics into actual processor instructions. (CO3) 1
- (a) Assembly language
 - (b) Machine language

- (c) Opcode
- (d) operand

- 1-d. The beginning and end of message queues are called the _____ & _____. (CO4) 1
- (a) tail and start
 - (b) tail and head
 - (c) head and tail
 - (d) Head and stop
- 1-e. If jobs have unpredictable release times a task is termed _____.(CO5) 1
- (a) aperiodic
 - (b) sporadic
 - (c) periodic.
 - (d) None of these

2. Attempt all parts:-

- 2.a. Difference between Hard and Soft Real time system. (CO1) 2
- 2.b. Why signal is called as asynchronous event. (CO2) 2
- 2.c. Write the meaning of '.src' file.(CO3) 2
- 2.d. What is the difference between queue and semaphore? (CO4) 2
- 2.e. What is the endianness? (CO5) 2

SECTION B

20

3. Answer any five of the following:-

- 3-a. What is an embedded system? Give at least two examples of embedded systems. (CO1) 4
- 3-b. Define Advantage and disadvantage of RTOS. (CO1) 4
- 3-c. Define intertask communication and its types. (CO2) 4
- 3-d. Explain message passing technique for inter process communication in detail. (CO2) 4
- 3.e. Describe Embedded Firmware Design Approach. (CO3) 4
- 3.f. Describe implementation of mutual exclusion using a mutex with help of diagram. (CO4) 4
- 3.g. Describe a priority inversion and priority elevation in RTX. (CO5) 4

SECTION C

35

4. Answer any one of the following:-

- 4-a. Difference between General Purpose OS & RTOS. Describe basic architecture of 7

an RTOS. (CO1)

4-b. State the main difference between logical and physical address space with an example. (CO1) 7

5. Answer any one of the following:-

5-a. Write a short note on Real time scheduling and Task Creation. (CO2) 7

5-b. Define Semaphores and Sockets. (CO2) 7

6. Answer any one of the following:-

6-a. Write a program in C for LCD test program using an Emulator. (CO3) 7

6-b. Describe in detail Integrated development environment (IDE). (CO3) 7

7. Answer any one of the following:-

7-a. What are the different types of scheduling queues? What is critical section in process synchronization?(CO4) 7

7-b. Write a short note on: (CO4) 7
i)Interrupt Management,
ii) Queues within an Interrupt Service Routine

8. Answer any one of the following:-

8-a. Briefly describe the features of the Cortex M3 based microcontrollers memory organization. (CO5) 7

8-b. Describe the Architecture of of CMSIS-RTOS. (CO5) 7