NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)



Affiliated to

DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY UTTAR PRADESH, LUCKNOW



Evaluation Scheme & Syllabus

For

Bachelor of Technology
Electronics and Communication Engineering

Third Year

(Effective from the Session: 2024-25)

NOIDA INSTITUTE OF ENGG. & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

Bachelor of Technology

Electronics and Communication Engineering

EVALUATION SCHEME

SEMESTER-V

| Sl. | Subject | Subject Name | Type of Subject | I | Peri | ods | F | Evaluati | ion Schem | e | Er Seme | | Total | Credit |
|-----|---------------------|--|--------------------------|----|------|------|-------|----------|-----------|----|------------|----|-------|--------|
| No. | Codes | | | L | T | P | CT | TA | TOTAL | PS | TE | PE | | |
| | , | WEEK | S COMPULSORY IN | DU | CTI | ON I | PROGR | RAM | 11 | | | | | |
| 1 | AEC0501 | Control System | Mandatory | 3 | 1 | 0 | 30 | 20 | 50 | | 100 | | 150 | 4 |
| 2 | AEC0502 | CMOS Digital Integrated Circuit | Mandatory | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 3 | AEC0503 | Electromagnetic Field Theory and Antenna | Mandatory | 3 | 1 | 0 | 30 | 20 | 50 | | 100 | | 150 | 4 |
| 4 | ACSE0503 | Design Thinking-II | Mandatory | 2 | 1 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 5 | | Departmental Elective -I | Departmental Elective | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 6 | | Departmental Elective -II | Departmental Elective | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 7 | AEC0551 | Control System Lab | Mandatory | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 8 | AEC0552 | CMOS Digital Integrated Circuit Lab | Mandatory | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 9 | | Departmental Elective Lab | Mandatory | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 10 | AEC0559 | Internship Assessment –II | Mandatory | 0 | 0 | 2 | | | | 50 | | | 50 | 1 |
| 11 | ANC0501/ ANC0502 | Constitution of India, Law and Engineering / Essence of Indian Traditional Knowledge | Compulsory Audit | 2 | 0 | 0 | 30 | 20 | 50 | | 50 | | 100 | NA |
| 12 | | *Massive Open Online Courses (For B.Tech. Hons. Degree) | *MOOCs | | | | | | | | | | | |
| | | GRAND TOTAL | | | | | | | | | | | 1100 | 24 |

* List of Recommended MOOCs (Massive Open Online Courses) for Third Year B. Tech Students (Semester-V)

| S. No. | Subject Code | Course Name | University / Industry Partner Name | No of Hours | Credits |
|-----------|-----------------|--|--|-------------|---------|
| 1 | AMC0304 | Wireless Evolution and 4G LTE Overview | Infosys Wingspan (Infosys Springboard) | 52h 4m | 4 |
| 2 | AMC0305 | C on Linux | Infosys Wingspan (Infosys Springboard) | 10h 20m | 0.5 |

PLEASE NOTE: -

- Internship (3-4 weeks) shall be conducted during summer break after semester-IV and will be assessed during Semester-V
- Compulsory Audit Courses (Non Credit ANC0501/ANC0502)
 - > All Compulsory Audit Courses (a qualifying exam) has no credit.
 - > Total and obtained marks are not added in the Grand Total.

Abbreviation Used:

List of Departmental Electives

| Sl. No. | Subject Codes | Subject Name | Type of Subject | Bucket Name | Branch | Semester |
|---------|---------------|--|---------------------------|-------------------------|--------|----------|
| 1 | AEC0511 | Applied Industrial IoT | Departmental Elective-I | | ECE | 5 |
| 2 | AEC0514 | IoT Architecture and Protocols | Departmental Elective-II | Internet of Things | ECE | 5 |
| 3 | AEC0511P | Applied IoT Lab | Departmental Elective Lab | - Timigs | ECE | 5 |
| 4 | AEC0512 | Embedded System Design | Departmental Elective-I | | ECE | 5 |
| 5 | AEC0515 | Introduction to Robotics and it's Applications | Departmental Elective-II | Embedded & Robotics | ECE | 5 |
| 6 | AEC0512P | Embedded System Design Lab | Departmental Elective Lab | | ECE | 5 |
| 7 | AEC0513 | Image Processing and Pattern Recognition | Departmental Elective-I | | ECE | 5 |
| 8 | AEC0516 | Machine Learning | Departmental Elective-II | Artificial Intelligence | ECE | 5 |
| 9 | AEC0513P | Image Processing and Pattern Recognition Lab | Departmental Elective Lab | | ECE | 5 |

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Bachelor of Technology

Electronics and Communication Engineering

EVALUATION SCHEME

SEMESTER-VI

| Sl. No | Subject | Subject Name | Type of | I | Period | ls | 1 | Evaluat | ion Scheme | 9 | Er Seme | | Total | Credit |
|-----------|----------------------|--|--------------------------|---|--------|----|----|---------|------------|----|------------|----|-------|--------|
| • | Codes | | Subject | L | T | P | CT | TA | TOTAL | PS | TE | PE | | |
| 1 | AEC0601 | Digital Signal Processing | Mandatory | 3 | 1 | 0 | 30 | 20 | 50 | | 100 | | 150 | 4 |
| 2 | AEC0602 | Wireless Communication Networks | Mandatory | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 3 | AEC0603 | 5G Technology | Mandatory | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 4 | | Departmental Elective-III | Departmental Elective | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 5 | | Departmental Elective-IV | Departmental Elective | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 6 | | Open Elective I | Open Elective | 3 | 0 | 0 | 30 | 20 | 50 | | 100 | | 150 | 3 |
| 7 | AEC0651 | Digital Signal Processing Lab | Mandatory | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 8 | AEC0652 | Wireless Communication Lab | Mandatory | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 9 | | Departmental Elective Lab | Departmental Elective | 0 | 0 | 2 | | | | 25 | | 25 | 50 | 1 |
| 10 | AEC0659 | Mini Project | Mandatory | 0 | 0 | 2 | | | | 50 | | | 50 | 1 |
| 11 | ANC0602 / ANC0601 | Essence of Indian Traditional Knowledge / Constitution of India, Law and Engineering | Compulsory Audit | 2 | 0 | 0 | 30 | 20 | 50 | | 50 | | 100 | NA |
| 12 | | *Massive Open Online Courses (For B.Tech. Hons. Degree) | *MOOCs | | | | | | | | | | | |
| | | GRAND TOTAL | | | | | | | | | | | 1100 | 23 |

* List of Recommended MOOCs (Massive Open Online Courses) for Third Year B. Tech Students (Semester-VI)

| S. No. | Subject Code | Course Name | University / Industry Partner Name | No of Hours | Credits |
|--------|-----------------|--------------------------------|--|-------------|---------|
| 1 | AMC0250 | Data Structures and Algorithms | Infosys Wingspan (Infosys Springboard) | 18h 5m | 1 |
| 2 | AMC0249 | Wireless 5G Overview | Infosys Wingspan (Infosys Springboard) | 55h 44m | 4 |
| 3 | AMC0282 | Introduction to ML and AI | Infosys Wingspan (Infosys Springboard) | 62h 54m | 4 |

PLEASE NOTE: -

- Internship (3-4 weeks) shall be conducted during summer break after semester-VI and will be assessed during semester-VII
- Compulsory Audit Courses (Non Credit ANC0601/ANC0602)
 - > All Compulsory Audit Courses (a qualifying exam) has no credit.
 - > Total and obtained marks are not added in the Grand Total.

Abbreviation Used:

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., CE: Core Elective, OE: Open Elective, DE: Departmental Elective, PE: Practical End Semester Exam, CA: Compulsory Audit, MOOCs: Massive Open Online Courses.

List of Departmental Electives

| S. No. | Subject Codes | Subject Name | Type of Subject | Bucket Name | Branch | Semester |
|-----------|------------------|--|---------------------------|-------------------------|--------|----------|
| 1 | AEC0611 | Privacy and Security in IoT | Departmental Elective-III | | ECE | 6 |
| 2 | AEC0614 | IoT Networks | Departmental Elective-IV | Internet of | ECE | 6 |
| 3 | AEC0614P | Advanced IoT and Mobile Applications Lab | Departmental Elective Lab | Things | ECE | 6 |
| 4 | AEC0612 | Real Time Operating System | Departmental Elective-III | F 1 11 10 | ECE | 6 |
| 5 | AEC0615 | Robotics Design Mechanism | Departmental Elective-IV | Embedded & Robotics | ECE | 6 |
| 6 | AEC0615P | Robotics Lab | Departmental Elective Lab | Roboties | ECE | 6 |
| 7 | AEC0613 | ANN & Deep Learning | Departmental Elective-III | | ECE | 6 |
| 8 | AEC0616 | Artificial Intelligence | Departmental Elective-IV | Artificial Intelligence | ECE | 6 |
| 9 | AEC0616P | AI & ML Lab | Departmental Elective Lab | miemgenee | ECE | 6 |

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Bachelor of Technology Electronics and Communication Engineering

AICTE Guidelines in Model Curriculum:

A student will be eligible to get Under Graduate degree with Honors only, if he/she completes the additional MOOCs courses such as Coursera certifications, or any other online courses recommended by the Institute (Equivalent to 20 credits). During Complete B.Tech. Program Guidelines for credit calculations are as follows.

| 1. | For 6 to 12 Hours | =0.5 Credit |
|----|-------------------|-------------|
| 2. | For 13 to 18 | =1 Credit |
| 3. | For 19 to 24 | =1.5 Credit |
| 4. | For 25 to 30 | =2 Credit |
| 5. | For 31 to 35 | =2.5 Credit |
| 6. | For 36 to 41 | =3 Credit |
| 7. | For 42 to 47 | =3.5 Credit |
| 8. | For 48 and above | =4 Credit |

For registration to MOOCs Courses, the students shall follow Coursera registration details as per the assigned login and password by the Institute these courses may be cleared during the B. Tech degree program (as per the list provided). After successful completion of these MOOCs courses, the students shall provide their successful completion status/certificates to the Controller of Examination (COE) of the Institute through their coordinators/Mentors only.

The students shall be awarded Honors Degree as per following criterion.

- i. If he / she secures 7.50 as above CGPA.
- ii. Passed each subject of that degree program in the single attempt without any grace.
- iii. Successful completion of MOOCs based 20 credits.

| | Bachelor of Technology Third Year | | |
|--|---|---------------------------------------|---|
| Course Code | AEC0501 | LTP | Credits |
| Course Title | Control System | 310 | 4 |
| Course Objectiv | res: The student will learn about | | |
| 1 | The basics of control systems along with different types of feedback and its effect. Introduction to techniques and signal flow graph | o block diagr | am reduction |
| 2 | Analysis of time domain response for various types of inputs along with the time domain specific | ations. | |
| 3 | Distinguish the concepts of absolute and relative stability for continuous data systems along with analyse the system stability. | different me | thods and |
| 4 | The concept the state space analysis of a control system. | | |
| 5 | The digital control system and its analysis. | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Introduction to Control Systems | | 8 hours |
| | n, Basic Components of a control system, types of Feedback and its effect, Introduction: open-loop Block diagram, Signal flow graph, Modelling a control system: Electrical network, Mechanical system, | | |
| UNIT-II Transient and ste | | , Servo moto | 8 hours |
| UNIT-II Transient and ste | Time Domain Analysis of Control Systems eady state response, Input test signal, Time response of a first order control system, Time response ate Error, Sensitivity, Design of Control system: PD, PI, PID controller | , Servo moto | 8 hours |
| UNIT-II Transient and ste system, steady sta UNIT-III Stability in terms | Block diagram, Signal flow graph, Modelling a control system: Electrical network, Mechanical system. Time Domain Analysis of Control Systems eady state response, Input test signal, Time response of a first order control system, Time response | e of a second | 8 hours order control 8 hours ontrol system |
| UNIT-II Transient and ste system, steady sta UNIT-III Stability in terms Nyquist stability system, | Time Domain Analysis of Control Systems eady state response, Input test signal, Time response of a first order control system, Time response ate Error, Sensitivity, Design of Control system: PD, PI, PID controller Stability of Control Systems s of characteristic equation, Routh Hurwitz criterion, Root-Locus Technique, Frequency domain as | e of a second | 8 hours order control 8 hours ontrol system |
| UNIT-II Transient and ste system, steady sta UNIT-III Stability in terms Nyquist stability system, UNIT-IV State space representations | Time Domain Analysis of Control Systems eady state response, Input test signal, Time response of a first order control system, Time response ate Error, Sensitivity, Design of Control system: PD, PI, PID controller Stability of Control Systems s of characteristic equation, Routh Hurwitz criterion, Root-Locus Technique, Frequency domain a criterion, stability analysis with the Bode plot, relative stability: gain margin and phase margin. | e of a second analysis of c Compensat | 8 hours 8 hours 8 hours ontrol systemion of control 8 hours |
| UNIT-II Transient and ste system, steady sta UNIT-III Stability in terms Nyquist stability system, UNIT-IV State space representations | Time Domain Analysis of Control Systems Pady state response, Input test signal, Time response of a first order control system, Time response at Error, Sensitivity, Design of Control system: PD, PI, PID controller Stability of Control Systems | e of a second analysis of c Compensat | 8 hours 8 hours 8 hours ontrol systemion of control 8 hours |

| CO 1 | Describe the basics of control systems along with different types of feedback and its effect. | K ₁ , K ₂ |
|------|--|---------------------------------|
| CO 2 | Interpret the time domain response analysis for various types of inputs along with the time domain specifications. | K ₃ , K ₄ |
| CO 3 | Distinguish the concepts of absolute and relative stability for continuous data systems along with different methods and analyse the system stability. | K ₃ , K ₄ |
| CO 4 | Analyse the nonlinear control system using the state space analysis. | K ₁ , K ₂ |
| CO 5 | Identify the digital control system and its analysis using z-transform. | K_1, K_3 |

Text books

- 1. I. J. Nagrath& M. Gopal, "Control System Engineering", 6th Ed. New Age International Publishers, 2018.
- 2. B.C. Kuo& Farid Golnaraghi, "Automatic Control Systems", 9th Edition, John Wiley India, 2008.

Reference Books

- 1. Norman S. Nise, "Control Systems Engineering", 7th Edition, John Wiley India.
- 2. Richard C. Dorf, Robert H. Bishop, "Modern Control Systems", 13th Edition, Pearson
- 3. Karl J. Åström, "Adaptive Control", Pearson Education India, 2006
- 4. M. Gopal, "Digital control System, 6th Ed. New Age International Publishers

NPTEL/ Youtube/ Faculty Video Link:

| Unit I | https://nptel.ac.in/courses/106/102/106102181/ |
|----------|--|
| | https://nptel.ac.in/courses/117/105/117105080/ |
| | https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK |
| Unit II | https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK |
| Unit III | https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK |
| Unit IV | https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK |
| Unit V | https://www.youtube.com/playlist?list=PLyqSpQzTE6M8-wda5vbgHkMQTmu-21hRK |

| Bachelor of Technology Third Year | | | | | |
|--|---|---|--|--|--|
| AEC0502 | LTP | Credits | | | |
| CMOS Digital Integrated Circuit | 300 | 3 | | | |
| nts will learn about | | | | | |
| MOS and CMOS logic gate design. | | | | | |
| CMOS Combinational and Sequential logic circuit design | | | | | |
| Dynamic logic circuit Design | | | | | |
| VLSI design methodology | | | | | |
| Different ASIC Design Flow | | | | | |
| vledge of MOSFET and Digital Electronics | | | | | |
| Course Contents/Syllabus | | | | | |
| MOSFET and CMOS Theory | | 8 hours | | | |
| | AEC0502 CMOS Digital Integrated Circuit Ints will learn about MOS and CMOS logic gate design. CMOS Combinational and Sequential logic circuit design Dynamic logic circuit Design VLSI design methodology Different ASIC Design Flow Vledge of MOSFET and Digital Electronics Course Contents/Syllabus | AEC0502 CMOS Digital Integrated Circuit Ints will learn about MOS and CMOS logic gate design. CMOS Combinational and Sequential logic circuit design Dynamic logic circuit Design VLSI design methodology Different ASIC Design Flow Vledge of MOSFET and Digital Electronics Course Contents/Syllabus | | | |

Evolution of VLSI, MOS threshold voltage, MOS device design equations, MOSFET scaling and small geometry effects, MOSFET capacitances. CMOS logic gate design: CMOS inverter, DC characteristics, rise time, fall time delays, noise margin, static & dynamic power dissipation, CMOS NAND, NOR, XOR and XNOR gates, Transistor sizing.

UNIT-II CMOS Combinational and Sequential logic circuit design 8 hours

CMOS Combinational Circuit: Design Half Adder, Full Adder, Multiplexers, Demultiplexers using CMOS.

CMOS Sequential logic circuits: Design SR latch, Simpler Implementation of SR Latch, JK flip flop, D flip flop using CMOS.

DAC: weighted resistor DAC, R-2R Ladder Type DAC.

ADC: Flash Type ADC, Dual Slope ADC, Successive approximation ADC.

UNIT-III Dynamic logic circuit Design

8 hours

Logic Gate design using pass transistor, different Combinational Circuit design using transmission gate and Pseudo NMOS logic.

Dynamic logic circuits: Basic principle, non-ideal effects, domino CMOS logic, high performance dynamic CMOS circuits, clocking issues, clock distribution.

UNIT IV VLSI Design Methodology 8 hours

VLSI design methodology, design Hierarchy, concept of regularity, modularity & locality, VLSI design style like Full Custom, Semi-Custom, Gate Array, Standard Cell and FPGA, design flow, Design quality Parameters, computer aided design technology, stick diagram and design rules, lambda-based design rules.

| UNIT-V | ASIC Design Flow | 8 hours |
|--------|------------------|---------|
| | | |

Introduction of Application Specific Integrated Circuit (ASIC) Design Flow: An overview of Backend VLSI Design Flow – Libraries, Floor-planning, Placement, Routing, Verification, Testing. Specifications and Schematic cell Design, Spice simulation Analysis of analog and digital circuits, Circuit Extraction, Electrical rule check, Layout Vs. Schematic (LVS), Post-layout Simulation and Parasitic extraction, Design format, Timing analysis, Back notation and Post layout simulation, ASIC design implementation.

Course Outcomes: After completion of this course students will be able to

| CO 1 | Express the concept of MOS design and CMOS logic gate design. | K1, K2 |
|------|---|------------|
| CO 2 | Design CMOS Combinational and Sequential logic circuit. | K1, K2, K3 |
| CO 3 | Implement various logic gate using Dynamic logic Technique. | K1, K2, K3 |
| CO 4 | Discuss the VLSI design methodology and its design flow. | K1, K2 |
| CO 5 | Describe ASIC Design Flow. | K1, K2, K3 |

Text Books:

- 1. Sung-Mo Kang &YosufLeblebici, "CMOS Digital Integrated Circuits: Analysis & Design", Mcgraw Hill, 4th Edition.
- 2. A.S. Sedra and K.C. Smith, "Microelectronic Circuits," Saunder's College 11 Publishing, 4th edition.

Reference Books:

- 1. Introduction to VLSI, Eshraghian&Pucknell, Tata McGraw-Hill Publishing Company Ltd., New Delhi, 2007
- 2. W.Wolf, Modern VLSI Design: System on Chip, Third Edition, Pearson, 2002.

| Unit 1 | https://www.youtube.com/watch?v=MuBiC9yz2fc |
|--------|--|
| Unit 2 | https://nptel.ac.in/courses/108/106/108106158, https://www.youtube.com/watch?v=UuafwIJAKhY |
| Unit 3 | https://www.youtube.com/watch?v=tRakiNOYBxI&t=19s |
| Unit 4 | https://www.youtube.com/watch?v=v2XywtRAHxM&t=2s, https://www.youtube.com/watch?v=N5vQIMyeA3M&t=1s |
| Unit 5 | https://nptel.ac.in/courses/117/101/117101058/ |

| | Bachelor of Technology Third Year | | |
|---|---|-------------------------|-----------------|
| Course Code | AEC0503 | LTP | Credits |
| Course Title Electromagnetic Field Theory and Antenna | | 310 | 4 |
| Course Objectives: | The student will learn about | | |
| 1 | Different coordinate systems, vector calculus, and their application in electroma | agnetic field theory. | |
| 2 | The concept of static Electric and Magnetic fields. | | |
| 3 | Maxwell's equations for time-varying fields, wave propagation in a different concepts of Electromagnetic radiation. | t medium, Poynting's Tl | heorem and basi |
| 4 | Fundamental properties of Antenna. | | |
| 5 | Practical Antennas and their applications. | | |
| Dro roquisitos: Ros | in fundamentals of vicators algebra | | |

Pre-requisites: Basic fundamentals of vectors algebra.

| Course Contents / Syl | labus | Hours |
|-----------------------|---------------------------------------|---------|
| UNIT-I | Coordinate Systems and Transformation | 8 hours |

Coordinates transformation: Cartesian, Cylindrical and Spherical. Vector calculus: Differential length, area and volume, line, surface and volume integrals, Del operator, Gradient, Divergence of a vector, Divergence theorem, Curl of a vector, Stokes's theorem, Laplacian of a scalar.

UNIT-II Electrostatic fields and Magnetostatic fields

8 hours

Electric field intensity, Electric field due to charge distribution, Electric flux density, Gauss's Law- Maxwell's equations, Continuity equation and relaxation time, boundary conditions, Magnetostatic fields, Ampere's circuit law, Maxwell's equation, magnetic scalar and vector potential, Magnetic boundary conditions.

UNIT-III Electromagnetic waves

8 hours

Maxwell's equations in final form, plane wave propagation in different medium: lossy dielectrics, lossless dielectrics, free space and good conductor, wave polarization, Poynting's theorem, radiation from small current element, power density and radiation resistance of short electric dipole and half wave dipole.

UNIT-IV Antenna fundamental

8 hours

Introduction, Basic antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Directivity and resolution, Antenna apertures, Effective height, The radio communication link.

UNIT-V Practical Antennas

8 hours

The Loop Antenna, Design and its Characteristic, Application of Loop Antennas. Horn Antennas, Helical Antennas, The Log-Periodic Antenna, Design of Microstrip Antenna, Parabolic Reflector Antennas, Feed Methods for Parabolic Reflectors.

| Course Outcomes: | Course Outcomes: After completion of this course students will be able to | | |
|-------------------------|---|--------|--|
| CO 1 | Apply different coordinate systems and vector calculus to solve problems of electromagnetic fields. | K3, K4 | |
| CO 2 | Explain and apply the concepts of static Electric and Magnetic fields. | K2, K3 | |
| CO 3 | Explain Maxwell's equations and their applications. | K2, K3 | |
| CO 4 | Explain and calculate the fundamental properties of Antenna. | K2, K4 | |
| CO 5 | Analyze practical Antennas with applications. | K2, K3 | |

Text Books:

- 1. MNO Sadiku, "Elements of Electromagnetics', Oxford University Press, 2014.
- 2. John D Kraus, Ronald J Marhefka and Ahmad S. Khan, "Antennas and Wave Propagation", Fourth Edition, Tata McGraw Hill, 2011.
- 3. C. A. Balanis, "Antenna Theory Analysis and Design", John Wiley, 2016.

Reference Books:

- 1. W H Hayt and JA Buck, "Engineering Electromagnetics", McGraw-Hill Education, 2013.
- 2. A. R. Harish, M. Sachidananda, "Antennas and Wave Propagation", Oxford University Press, 2007.
- 3. R. L. Yadava, Electromagnetic Waves, Khanna Publishing House, Delhi, 2018.
- 4. A. Das, Sisir K. Das, "Microwave Engineering", Tata McGraw Hill, 2001.

NPTEL/ Youtube/ Faculty Video Link:

| Unit 1 | https://www.youtube.com/watch?v=3qd1JT7sRG8 |
|--------|---|
| Unit 2 | https://www.youtube.com/watch?v=F5KFYBdjzuE&list=PLVFqK_9GOGXnV8fwd2YmUURVmECpCIShv |
| Unit 3 | https://www.youtube.com/watch?v=7NZhmOIyYQM |
| Unit 4 | https://www.youtube.com/watch?v=h51mFbIgZRI&list=PLbRMhDVUMngfytbQXzasPMHuWst4E-Ly8&index=2 |
| Unit 5 | https://www.youtube.com/watch?v=wx_tIvaajAI&list=PL3UZlxOnyu9CRoBFsG5x-VqYeC69FmMZT |

| | Bachelor of Technology Third Year | | | |
|--|-----------------------------------|-----|---|--|
| Course Code ACSE0503 LTP Credits | | | | |
| Course Title | DESIGN THINKING II | 210 | 3 | |

Course Objectives:

The objective of this course is to upgrade Design Thinking skills by learning & applying advanced and contextual Design Thinking Tools. It aims to solve a Real-Life Problem by applying Design Thinking to create an impact for all the stakeholders

Pre-requisites: Student must complete Design Thinking-I course

Course Contents / Syllabus

UNIT-I Introduction 10 HOURS

Design thinking & Innovation, Design Thinking Mindset and Principles, recap of 5-Step Process of Design Thinking, Design Approaches, additional in-depth examples of each design approaches. Simon Sinek's – Start with Why, The Golden Circle, Asking the "Why" behind each example (an in-class activity of asking 5-WHYS), The Higher Purpose, in-class activity for LDO & sharing insights

Visualization and it's importance in design thinking, reflections on wheel of life (*in-class activity for visualization & Wheel of Life*), Linking it with Balancing Priorities (*in class activity*), DBS Singapore and Bank of Americas' Keep the Change Campaign. Litter of Light & Arvind Eye Care Examples, understanding practical application of design thinking tools and concepts, case study on McDonald's Milkshake / Amazon India's Rural Ecommerce & Gillette

Working on 1-hour Design problem, Applying RCA and Brainstorm on innovative solutions.

Main project allocation and expectations from the project

UNIT-II Refinement and Prototyping 8 HOURS

Refine and narrow down to the best idea, 10-100-1000gm, QBL, Design Tools for Convergence – SWOT Analysis for 1000gm discussion. *Inclass activity for 10-100-1000gm & OBL*

Prototyping (Convergence): Prototyping mindset, tools for prototyping – Sketching, paper models, pseudo-codes, physical mockups, Interaction flows, storyboards, acting/role-playing etc, importance of garnering user feedback for revisiting Brainstormed ideas,

Napkin Pitch, Usability, Minimum Viable Prototype, Connecting Prototype with 3 Laws, A/B Testing, Learning Launch. Decision Making Tools and Approaches – Vroom Yetton Matrix, Shift-Left,Up,Right, Value Proposition, Case study: Careerbuddy,You-Me-Health Story & IBM

Learning Launch.

In-class activities on prototyping- paper-pen / physical prototype/ digital prototype of project's 1000gm idea

| UNIT-III | Storytelling, Testing and Assessment | 8 HOURS |
|----------|--------------------------------------|---------|
| | | |

Storytelling: Elements of storytelling, Mapping personas with storytelling, Art of influencing, Elevator Pitch, Successful Campaigns of well-known examples, *in-class activity on storytelling*.

Testing of design with people, conducting usability test, testing as hypothesis, testing as empathy, observation and shadowing methods, Guerrilla Interviews, validation workshops, user feedback, record results, enhance, retest, and refine design, Software validation tools, design parameters, alpha&beta testing, Taguchi, defect classification, random sampling

Final Project Presentation and assessing the impact of using design thinking

UNIT-IV Innovation, Quality and Leadership 6 HOURS

Innovation: Need & Importance, Principles of innovations, Asking the Right Questions for innovation, Rationale for innovation, Quality: Principles & Philosophies, Customer perception on quality, Kaizen, 6 Sigma. *FinTech case study of Design Thinking application – CANVAS*Leadership, types, qualities and traits of leaders and leadership styles, Leaders vs Manager, Personas of Leaders & Managers, Connecting Leaders-Managers with 13 Musical Notes, Trait theory, LSM (Leadership Situational Model), Team Building Models: Tuckman's and Belbin's. Importance of Spatial elements for innovation

UNIT-V Understanding Human Desirability 8 HOURS

Program needed to achieve the comprehensive human goal: the five dimensions of human endeavour(ManaviyaVyavstha) are: Education-Right living (Sikhsa-Sanskar), Health – Self-regulation (SwasthyaSanyam), Justice – Preservation (Nyaya-Suraksha), Production – Work (Utpadan – Karya), Exchange – Storage (Vinimya – Kosh), Darshan-Gyan-Charitra (Shifting the Thinking)

Interconnectedness and mutual fulfilment among the four orders of nature recyclability and self-regulation in nature, Thinking expansion for harmony: Self-exploration (Johari's window), group behaviour, interpersonal behaviour and skills, Myers-Briggs personality types (MBTI), FIRO-B test to repair relationships.

Course outcome: After completion of this course, students will be able to

| CO 1 | Learn sophisticated design tools to sharpen their problem-solving skills | K2 |
|------|---|--------|
| CO 2 | Generate innovate ideas using design thinking tools and converge to feasible idea for breakthrough solution | K3, K4 |
| CO 3 | Implement storytelling for persuasive articulation | K3 |
| CO 4 | Understanding the nature of leadership empowerment | K2 |

| CO 5 | Understand the role of a human being in ensuring harmony in society and nature. | K2 |
|------|---|----|
| | | |

Textbooks

- 1. Arun Jain, UnMukt: Science & Art of Design Thinking, 2020, Polaris
- 2. Gavin Ambrose and Paul Harris, Basics Design 08: Design Thinking, 2010, AVA Publishing SA
- 3. R R Gaur, R Sangal, G P Bagaria, A Foundation Course in Human Values and Professional Ethics, First Edition, 2009, Excel Books: New Delhi

Reference Books

- 1. Jeanne Liedta, Andrew King and Kevin Benett, Solving Problems with Design Thinking Ten Stories of What Works, 2013, Columbia Business School Publishing
- 2. Dr RituSoryan, Universal Human Values and Professional Ethics, 2022, Katson Books
- 3. Vijay Kumar, 101 Design Methods: A Structured Approach for Driving Innovation in Your Organization, 2013, John Wiley and Sons Inc, New Jersey
- 4. Roger L. Martin, Design of Business: Why Design Thinking is the Next Competitive Advantage, 2009, Harvard Business Press, Boston MA
- 5. Tim Brown, Change by Design, 2009, Harper Collins
- 6. Pavan Soni, Design your Thinking: The Mindsets, Toolsets and Skill Sets for Creative Problem-Solving, 2020, Penguin Books

NPTEL/ YouTube/ Web Link

Unit I https://www.youtube.com/watch?v=6_mHCOAAEI8

https://nptel.ac.in/courses/110106124

https://designthinking.ideo.com/

https://blog.experiencepoint.com/how-mcdonalds-evolved-with-design-thinking

Unit II https://www.coursera.org/lecture/uva-darden-design-thinking-innovation/the-ibm-story-iq0kE

 $\underline{https://www.coursera.org/lecture/uva-darden-design-thinking-innovation/the-meyouhealth-story-part-i-what-is-W6tTs}$

https://onlinecourses.nptel.ac.in/noc19 mg60/preview

Unit III https://nptel.ac.in/courses/109/104/109104109/

https://www.d-thinking.com/2021/07/01/how-to-use-storytelling-in-design-thinking/

Unit IV https://www.worldofinsights.co/2020/10/infographic-8-design-thinking-skills-for-leadership-development/

Unit V https://www.youtube.com/watch?v=hFGVcx1Us5Y

| | Bachelor of Technology | Thir | rd Year |
|---|---|-------|--|
| Course Code | | | Credits |
| Course Title | Applied Industrial IoT 3 0 | 0 | 3 |
| Course Objec | tives: Student will learn about | | |
| 1 | The basic introduction and layered architecture of IIoT. | | |
| 2 | The technology used in various types of sensors and measurement | nt. | |
| 3 | Different functionalities required for edge computing and gatewa | ıy. | |
| 4 | The architecture, big data architecture and data configure archite | |). |
| 5 | The security threats and gaps and provide the security solution. | | |
| Pre-requisites | : Knowledge of basic fundamentals of IoT. | | |
| - | Course Contents / S | yllab | ous |
| UNIT-I | Introduction to Industrial IoT | | 8 hours |
| Concept of In | ternet of Things, Drivers, Benefits and Challenges of IoT, C | atego | ories of IoT, Examples of IoT in Industry, Layers of IIoT |
| Architecture, | Functions of HoT Architecture Layers, Components of HoT | Arch | itecture, Review of Components in various layers of IoT, |
| Components of | f M bed operating system and its functionalities. | | |
| UNIT-II | Data Acquisition and Measurement | | 8 hours |
| a m 1 | | | |
| Sensor Techno | logies, Thermal Sensors, Pressure, Shear and Photo Sensors, Elec- | rical | , Magnetic and |
| | logies, Thermal Sensors, Pressure, Shear and Photo Sensors, Electensors, Introduction to Measurements, Direct Measurement, In | | <u> </u> |
| | ensors, Introduction to Measurements, Direct Measurement, In | | <u> </u> |
| Mechanical So Industrial Syste UNIT-III | ensors, Introduction to Measurements, Direct Measurement, International Edge Computing and Gateway | direc | et Measurement, Derived Measurement, Measurement from 8 hours |
| Mechanical So Industrial Syste UNIT-III | ensors, Introduction to Measurements, Direct Measurement, International Control of the Measurements of the Measurement of the Measurements of the Measurement of the | direc | et Measurement, Derived Measurement, Measurement from 8 hours |
| Mechanical So Industrial Syste UNIT-III | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice | direc | et Measurement, Derived Measurement, Measurement from 8 hours |
| Mechanical Se Industrial Syste UNIT-III Edge Computi | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice | direc | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and |
| Mechanical Se Industrial Syste UNIT-III Edge Computi Quality Contro UNIT-IV | ensors, Introduction to Measurements, Direct Measurement, Interest. Edge Computing and Gateway Interest | of (| t Measurement, Derived Measurement, Measurement from 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and 8 hours |
| Mechanical Se Industrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture | of (| t Measurement, Derived Measurement, Measurement from 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and 8 hours |
| Mechanical Se Industrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture er Architecture, Data Architecture, Big Data Architecture and Street | of (| 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and 8 hours Processing, Storage Devices, Storage Technologies, Analytics |
| Mechanical Second Industrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server Overview, Type UNIT-V | ensors, Introduction to Measurements, Direct Measurement, Interest. Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture er Architecture, Data Architecture, Big Data Architecture and Streets of Analytics. | of C | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and Processing, Storage Devices, Storage Technologies, Analytics 8 hours |
| Mechanical Se Industrial Syste UNIT-III Edge Computi Quality Control UNIT-IV Types of Serve Overview, Typ UNIT-V IIoT Device S | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway Ing, Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture Per Architecture, Data Architecture, Big Data Architecture and Streets of Analytics. IIoT Security | of C | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and Processing, Storage Devices, Storage Technologies, Analytics 8 hours |
| Mechanical Se Industrial Syste UNIT-III Edge Computi Quality Control UNIT-IV Types of Serve Overview, Typ UNIT-V IIoT Device S Connected Wo | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway Ing., Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture Par Architecture, Data Architecture, Big Data Architecture and Strees of Analytics. InoT Security Security, IIoT Connection Security, IIoT Application Platform as | of C | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and Processing, Storage Devices, Storage Technologies, Analytics 8 hours |
| Mechanical Se Industrial Syste UNIT-III Edge Computi Quality Control UNIT-IV Types of Serve Overview, Typ UNIT-V IIoT Device S Connected Wo | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway Ing, Gateway Overview, Types and Features of Gateway, Choice at the Edge. Platform Architecture Pracritecture, Data Architecture, Big Data Architecture and Strees of Analytics. IIoT Security Recurity, IIoT Connection Security, IIoT Application Platform arkplace Solution. | of C | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and 8 hours Processing, Storage Devices, Storage Technologies, Analytics 8 hours Cloud Security, Threat Modeling, Industrial Example – IoT |
| Mechanical Second Industrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server Overview, Type UNIT-V IIoT Device Second Course Outco | ensors, Introduction to Measurements, Direct Measurement, Interns. Edge Computing and Gateway Ing, Gateway Overview, Types and Features of Gateway, Choice of at the Edge. Platform Architecture Per Architecture, Data Architecture, Big Data Architecture and Strees of Analytics. IIoT Security Security, IIoT Connection Security, IIoT Application Platform arkplace Solution. mes: After completion of this course students will be able to | of C | 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and Processing, Storage Devices, Storage Technologies, Analytics 8 hours |
| Mechanical Second Industrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server Overview, Type UNIT-V Hot Device Second Course Outco | Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice at the Edge. Platform Architecture Practice Architecture, Data Architecture, Big Data Architecture and Strees of Analytics. HoT Security Becurity, HoT Connection Security, HoT Application Platform arkplace Solution. mes: After completion of this course students will be able to Analyze the scope and impact of IoT in daily life, society and | of (| 8 hours Gateway, Configuring the Gateway, IoT Video Analytics and 8 hours Processing, Storage Devices, Storage Technologies, Analytics 8 hours Cloud Security, Threat Modeling, Industrial Example – IoT |
| Mechanical Secondustrial System UNIT-III Edge Computing Quality Control UNIT-IV Types of Server Overview, Type UNIT-V IIoT Device Secondustrial Connected Wood | Edge Computing and Gateway ng, Gateway Overview, Types and Features of Gateway, Choice at the Edge. Platform Architecture er Architecture, Data Architecture, Big Data Architecture and Strees of Analytics. HoT Security decurity, HoT Connection Security, HoT Application Platform arkplace Solution. mes: After completion of this course students will be able to Analyze the scope and impact of IoT in daily life, society and Industry and able to architect the layers of HoT. | of (| The Measurement, Derived Measurement, Measurement from 8 hours and 8 hours and 8 hours Processing, Storage Devices, Storage Technologies, Analytics 8 hours and 8 hours Cloud Security, Threat Modeling, Industrial Example – IoT K_1, K_2 |

| CO 3 | Identify the various functionalities that are required in edge | K_1, K_2 | |
|-------------------|---|-----------------|--|
| | computing and gateway. | | |
| CO 4 | Explain platform architecture, big data architecture and to configure | K_1, K_2 | |
| | the data storage architecture. | | |
| CO 5 | Foresee possible security threats including gaps and identify its | K_1, K_2 | |
| | solutions. | | |
| Text books | | | |
| 1. Guang Zho | ou, China, Industrial IoT Technologies and Applications, 2016, Kindle | Edition | |
| 2. Timothy Cl | hou Precision - Principles, Practices and Solutions for the Internet of T | hings, 2016 PHI | |
| Reference Boo | oks | | |
| 1. Mahmood, | 1. Mahmood, Marchenko, Wireless Networks and Industrial IoT: Applications, Challenges and Enablers 1st ed. 2021 Edition, Kindle Edition | | |
| 2. Ismail Butu | 2. Ismail Butun, Industrial IoT: Challenges, Design Principles, Applications, and Security, Kindle Edition | | |
| NPTEL/ Yout | rube/ Faculty Video Link: | | |
| Unit 1 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=51 | | |
| Unit 2 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=57&lesson=58 | | |
| Unit 3 | https://www.youtube.com/watch?v=QnK0rf3y69s | | |
| Unit 4 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=33&lesson=38 | | |
| | | | |

| | Bachelor of Technology Third Year | | |
|------------------------|--|---------------------|--|
| Course Code | AEC0512 | LTP | Credits |
| Course Title | Embedded Systems Design | 3 0 0 | 3 |
| Course Object | ives: Student will learn about | 1 | |
| 1 | Understand the basic introduction to embedded system design requirements. | | |
| 2 | Learn the STM32F401 board & its interfacing. | | |
| 3 | Understand the Architecture of ARM CORTEX-M4 processor. | | |
| 4 | Learn the programming techniques of ARM processor. | | |
| 5 | Understand the concept of embedded Linux and Linux kernel architecture. | | |
| Pre-requisites: | Knowledge of Microprocessor and Microcontroller | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Embedded System Concepts | | 8 hours |
| | Embedded Systems: Definition of Embedded System, Embedded Systems Vs General Co | | _ |
| • | fication, Major Application Areas, Purpose of Embedded Systems, Design Considerations | of Embedded Syste | |
| UNIT-II | STM32F401 Board & Interfacing | | 8 hours |
| | ucleo Board, Interfacing with Analog World, Output Devices, Sensors and Actuators, Int | erfacing with 7 seg | ment LED and LCD |
| | facing with Temperature Sensor and LDR Light Sensor, Speed Control of DC Motor. | | |
| UNIT-III | The ARM CORTEX-M4 Processor | | 8 hours |
| | Arm architectures and processors, Structure and purpose of specific registers in the Arm (| | |
| | upt Controller (NVIC), Wakeup Interrupt Controller (WIC), Memory Protection Unit (MP | U), Bus Interconnec | ct and Debug System |
| and Low Power | <u> </u> | | 0.1 |
| UNIT-IV | ARM CORTEX-M4 Programming | T 1 . 11 | 8 hours |
| | Arm Cortex-M4 Programming, Compare the C and Assembly programming languages, C | | |
| | rawbacks of high-level and low-level programming, Introduction to the Mbed Platfor | m and CMSIS, M | bed platform and its |
| importance. | E.I.II.II'. OD' | | 0.1 |
| UNIT-V | Embedded Linux & Drivers | 1 1 1 CF 1 | 8 hours |
| • | bedded Linux, Embedded Linux versus Desktop Linux, Embedded Linux Distributions, A | | bedded Linux, Linux |
| Kernel Architec | cture, Linux Start-Up Sequence, GNU Cross-p\Platform Tool chain, Linux Serial Driver, E | thernet Driver. | |
| Course Outcom | nes: After completion of this course students will be able to | | |
| CO 1 | Compute the design considerations of embedded systems. | | K_1, K_2 |
| CO 2 | Apply the knowledge to learn STM32F401 for various application. | | K ₁ , K ₃ , K ₄ |
| CO 3 | Analyze the Architecture of ARM CORTEX-M4 processor. | | K ₃ , K ₄ |
| | | | |

| CO 4 | Implement the programming techniques for ARM processor. | K ₃ , K ₄ | | | |
|---|---|--|--|--|--|
| CO 5 | Evaluate the concept of embedded Linux and kernel architecture. | K ₂ , K ₄ , K ₅ | | | |
| Text books | | | | | |
| 1.ARM system developers guide, Andrew N Sloss, Dominic Symes and Chris Wright, Elsevier, Morgan Kaufman publishers, 2008. | | | | | |
| | | | | | |
| 2. The Definit | ive Guide to the ARM Cortex-M3, by Joseph Yiu, 2nd Edition, Newnes, 2009 | | | | |
| 3. Embedded | Linux System Design and Development, P.Raghavan, Amol Lad, Sriram | | | | |
| Neelakandan, | Neelakandan, 2006, Auerbach Publications. | | | | |
| Reference Bo | oks | | | | |
| 1. Shibu K V, | —Introduction to Embedded Systems, Tata McGraw Hill Education Private Limited, 2009. | | | | |
| 2. Embedded | Systems: Architecture, Programming and design, Raj Kamal, Second Edition, Tata McGraw Hill pu | ıblisher, 2010. | | | |
| 3. David E. Si | mon, "An Embedded Software Primer", Pearson Education. | | | | |
| 4. ARM Syste | em-on-Chip Architecture, Steve Furber, Second Edition, Pearson, 2015 | | | | |
| NPTEL Link | S | | | | |
| Unit 1 | Unit 1 https://www.youtube.com/watch?v=y9RAhEfLfJs | | | | |
| Unit 2 | | | | | |
| Unit 3 | https://nptel.ac.in/courses/106/105/106105193/ | | | | |
| Unit 4 | https://www.youtube.com/watch?v=csttt3VHxf8 | | | | |
| Unit 5 | https://www.youtube.com/watch?v=h-ZP98qhEM8 | | | | |

| | Bachelor of Technology Third Year | | |
|--|--|--|---|
| Course Code | AEC0513 | LTP | Credits |
| Course Title | Image Processing and Pattern Recognition | 300 | 3 |
| Course Objective: T | he student will learn about | | |
| 1 | Basics of digital image and various operations on it. | | |
| 2 | Image enhancement techniques in different domains. | | |
| 3 | The various noises in images and restoration methods. | | |
| 4 | Skills to segment a digital image with different methods. | | |
| 5 | The basics of colour image processing and various image compre | ssion techn | iques. |
| Pre-requisites: Basic | fundamental of mathematics and signal processing | | |
| | Course Contents / Syllabus | | Hours |
| UNIT-I | Introduction To Image Processing & Image Formation | | 8 Hours |
| Basic image file form | ats, Geometric and photometric models, Image Sensing and Acquisiti | on, Image S | Sampling and Quantization, Basic |
| Relationship between | Pixels, Linear and Nonlinear Operations on digital images, Applicat | ions of DIP | |
| UNIT-II | Image Enhancement | | 8 Hours |
| | sic Gray Level Transformations, Histogram based Processing, Enhanced Pro | ncement us | ing Arithmetic/Logic Operations |
| Spatial Filtering, Smo Frequency Domain: Selective Filtering. | oothing and Sharpening by Spatial Filtering. Filtering in the Frequency Domain, Image Smoothing and Image S | | Using Frequency Domain Filters |
| Spatial Filtering, Smo Frequency Domain: Selective Filtering. UNIT-III | oothing and Sharpening by Spatial Filtering. Filtering in the Frequency Domain, Image Smoothing and Image S Image Restoration | Sharpening | Using Frequency Domain Filters 8 Hours |
| Spatial Filtering, Smo Frequency Domain: Selective Filtering. UNIT-III Image Degradation/R | oothing and Sharpening by Spatial Filtering. Filtering in the Frequency Domain, Image Smoothing and Image S | Sharpening | Using Frequency Domain Filters 8 Hours |
| Spatial Filtering, Smo Frequency Domain: Selective Filtering. UNIT-III Image Degradation/R noise reduction by fre | Image Restoration estoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction | Sharpening nce of nois | Using Frequency Domain Filters. 8 Hours se only–spatial filtering, Periodic 8 Hours |
| Spatial Filtering, Smore Frequency Domain: Selective Filtering. UNIT-III Image Degradation/R noise reduction by free UNIT-IV Edge Linking and Bow Watershed, K-means | Image Restoration Sestoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction oundary Detection, Thresholding: Otsu and adaptive, Region-Based and Fuzzy C-means, Wavelet transform, Discrete wavelet transform matrix; Moments; Connected component analysis; Convex hull; | Sharpening nce of noise Segmentation, Hough tr | Using Frequency Domain Filters. 8 Hours se only–spatial filtering, Periodic 8 Hours on, Segmentation: Morphological ransform, Textural features - grey |
| Spatial Filtering, Smore Frequency Domain: Selective Filtering. UNIT-III Image Degradation/Reprise reduction by free UNIT-IV Edge Linking and Boy Watershed, K-means level co-occurrence in the second secon | Image Restoration Sestoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction oundary Detection, Thresholding: Otsu and adaptive, Region-Based and Fuzzy C-means, Wavelet transform, Discrete wavelet transform matrix; Moments; Connected component analysis; Convex hull; | Sharpening nce of noise Segmentation, Hough tr | Using Frequency Domain Filters 8 Hours se only–spatial filtering, Periodic 8 Hours on, Segmentation: Morphological ransform, Textural features - grey |
| Spatial Filtering, Smore Frequency Domain: Selective Filtering. UNIT-III Image Degradation/Renoise reduction by free UNIT-IV Edge Linking and Bow Watershed, K-means level co-occurrence skeletonization/thinning UNIT-V Fundamentals of difference of the selection | Image Restoration Sestoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction oundary Detection, Thresholding: Otsu and adaptive, Region-Based and Fuzzy C-means, Wavelet transform, Discrete wavelet transform matrix; Moments; Connected component analysis; Convex hull; ing, shape properties. | Sharpening nce of noise Segmentation, Hough truly Distance truly | Using Frequency Domain Filters 8 Hours e only–spatial filtering, Periodic 8 Hours on, Segmentation: Morphological ransform, Textural features - grey ransform, medial axis transform 8 Hours |
| Spatial Filtering, Smore Frequency Domain: Selective Filtering. UNIT-III Image Degradation/Remoise reduction by free UNIT-IV Edge Linking and Bow Watershed, K-means level co-occurrence skeletonization/thinning UNIT-V Fundamentals of difference of the Dilation and Erosion of the Dilation and Erosion of the UNIT-V | Image Restoration Restoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction oundary Detection, Thresholding: Otsu and adaptive, Region-Based and Fuzzy C-means, Wavelet transform, Discrete wavelet transform matrix; Moments; Connected component analysis; Convex hull; ing, shape properties. Color Image Processing & Morphological Filtering Basics erent colour models - RGB, CMY, HSI, YCbCr, Lab; False colour; | Sharpening nce of noise Segmentation, Hough truly Distance truly | Using Frequency Domain Filters 8 Hours 9 e only–spatial filtering, Periodic 8 Hours 10 on, Segmentation: Morphological ransform, Textural features - grey ransform, medial axis transform. 8 Hours |
| Spatial Filtering, Smore Frequency Domain: Selective Filtering. UNIT-III Image Degradation/Remoise reduction by free UNIT-IV Edge Linking and Bow Watershed, K-means level co-occurrence skeletonization/thinning UNIT-V Fundamentals of difference of the Dilation and Erosion of the Dilation and Erosion of the UNIT-V | Image Restoration Restoration process model, Noise Models, Restoration in the present equency domain filtering. Image Segmentation & Image/Object Features Extraction oundary Detection, Thresholding: Otsu and adaptive, Region-Based and Fuzzy C-means, Wavelet transform, Discrete wavelet transform matrix; Moments; Connected component analysis; Convex hull; Ing, shape properties. Color Image Processing & Morphological Filtering Basics erent colour models - RGB, CMY, HSI, YCbCr, Lab; False colour; Operators, Top Hat Filters. | Sharpening nce of nois Segmentation, Hough tr Distance tr | Using Frequency Domain Filters 8 Hours 9 e only–spatial filtering, Periodic 8 Hours 10 on, Segmentation: Morphological ransform, Textural features - grey ransform, medial axis transform. 8 Hours |

| CO 3 | Recognize various noises in images and apply restoration methods. | K3, K4 |
|----------|--|--------|
| CO 4 | Apply different segmentation techniques on image. | K3 |
| CO 5 | Perform different operations on colour images as well as different morphological filtering techniques on images to analyse them. | K2, K3 |
| 7D 4 D 1 | | |

Text Books:

- 3. Rafael C. Gonzalez, Richard E. Woods, Digital Image Processing Pearson, Third Edition, 2010.", Prentice Hall of India.
- 4. Anil K. Jain, Fundamentals of Digital Image Processing Pearson, 2002.

Reference Books:

- 1. Milan Sonka, Vaclav Hlavav, Roger Boyle, —Image Processing, Analysis and Machine Vision, 2nd ed., Thomson Learning, 2001.
- 2. Rangaraj M. Rangayyan, —Biomedical Image Analysis, CRC Press, 2005
- 3. Pratt W.K, —Digital Image Processing, 3rd ed., John Wiley & Sons, 2007
- 4. Digital Image Processing, 3rd Edition, by Rafael C Gonzalez and Richard E Woods. Publisher: Pearson Education

NPTEL/ Youtube/ Faculty Video Link:

| Unit 1 | https://youtu.be/T0bgf3V7u-E |
|--------|------------------------------|
| | https://youtu.be/bJjgyTQ-BT4 |
| Unit 2 | https://youtu.be/M7JxDHUW5cc |
| | https://youtu.be/JfrcMYBouJE |
| Unit 3 | https://youtu.be/MrNafUqh860 |
| Omt 5 | https://youtu.be/gLTlQPYY_pw |
| Unit 4 | https://youtu.be/j3_Ck5oP5oI |
| | https://youtu.be/q1J0VAYFkHg |
| Unit 5 | https://youtu.be/kSzramCsHA4 |
| Omt 5 | https://youtu.be/nlwH07G9Efg |

| | Rachelo | r of Technology Third Year | |
|--|--|---|--|
| Course Code | AEC0514 | LTP | Credits |
| Course Title | IoT Architecture and Protocols | 3 0 0 | 3 |
| Course Object | tives: Student will learn about | | |
| 1 | The architectural overview and IoT reference | architecture. | 1 |
| 2 | The open source architecture and design principles. | | |
| 3 | The various types of IoT connectivity protocols. | | |
| 4 | Different types of IoT layered protocols. | | |
| 5 | Differences between Web of things and Inter- | net of things. | |
| Pre-requisites: | : Knowledge of basic fundamentals of IoT | | |
| | Ĭ | rse Contents / Syllabus | |
| UNIT-I | Reference Architecture | • | 8 hours |
| IoT-An Archit | tectural Overview- Building an architecture, | Main design principles and | needed capabilities, IoT Reference Architecture- |
| Introduction, F | Functional View, Information View, Deploymen | nt and Operational View, Othe | r Relevant architectural views. Real-World Design |
| Constraints- In | troduction, Technical Design constraints, Data | representation and visualization | on, Interaction and remote control, Wireless Sensor |
| Network. | | | |
| UNIT-II | IoT Architecture | | 8 hours |
| - | | | deployment models- IoTivity: An Open source IoT |
| | ew- IoTivity stack architecture- Resource mode | l and Abstraction. LoRaWAN | architecture, Channel access mechanism specific to |
| NB-IoT. | | | |
| UNIT-III | IoT Connectivity Protocols | | 8 hours |
| | | otocols, LAN Protocols, Serial | Protocols, IoT transmission Protocols, Wired LAN |
| | ures and security in Bluetooth | | T |
| UNIT-IV | IoT Layered Protocols | | 8 hours |
| | | | ocols, Issues with IoT Standardization, Unified Data |
| | | | |
| | | rotocol Modbus, KNX, archite | ecture and Protocol stack used in Zig bee, Network |
| layer, APS laye | er. | Protocol Modbus, KNX, archite | |
| layer, APS laye | Web of Things | | 8 hours |
| layer, APS laye UNIT-V Web of Things | Web of Things versus Internet of Things, Two Pillars of the W | eb, Architecture Standardization | |
| layer, APS laye UNIT-V Web of Things | Web of Things | eb, Architecture Standardization | 8 hours |
| layer, APS laye UNIT-V Web of Things Multitier WoT | Web of Things versus Internet of Things, Two Pillars of the W | Veb, Architecture Standardization | 8 hours |
| layer, APS laye UNIT-V Web of Things Multitier WoT | Web of Things versus Internet of Things, Two Pillars of the W Architecture, WoTPortals and Business Intelligence | eb, Architecture Standardization ence. will be able to | 8 hours |

| CO 3 | Analyze the various types of IoT connectivity protocols. | K1 | | |
|-----------------|---|---|--|--|
| CO 4 | Explain the different types of IoT layered protocols. | K1, K2 | | |
| CO 5 | Describe the differences between Web of things and Internet of Things. | K1, K2 | | |
| Text books | | | | |
| 1. Honbo | 1. Honbo Zhou, "The Internet of Things in the Cloud: A Middleware Perspective", CRC Press, 2012 | | | |
| 2. Dieter | 2. Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds), "Architecting the Internet of Things", Springer, 2011 | | | |
| | 3. David Easley and Jon Kleinberg, "Networks, Crowds, and Markets: Reasoning About a Highly Connected World", Cambridge University Press, 2010. | | | |
| Reference Boo | oks | | | |
| 1. Vijay N | 1. Vijay Madisetti and ArshdeepBahga, "Internet of Things (A Hands-on-Approach)",1st Edition, VPT, 2014. | | | |
| 2. Francis 2013 | daCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Eve | rything", 1st Edition, Apress Publications, | | |

3. Cuno P fister, Getting Started with the Internet of Things, O" Reilly Media, 2011, ISBN: 978-1

https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=53

https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=20

https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=19

https://www.youtube.com/watch?v=FRxRT0DjE7A

https://www.youtube.com/watch?v=R52OCMtFqNA

NPTEL/ Youtube/ Faculty Video Link:

Unit 1

Unit 2

Unit 3

Unit 4

Unit 5

| 0 0 1 | Bachelor of Technology Thi | ira year | |
|--|--|--|--|
| Course Code | AEC0515 | LTP | Credits |
| Course Title | Introduction to Robotics & Its Applications | 3 0 0 | 3 |
| Course Object | ives: Student will learn about | | |
| 1 | The concept of robotics. | | - |
| 2 | Mathematical relations for forward and inverse kinematic analysis. | | |
| 3 | The various types of actuators and drive systems. | | |
| 4 | Different types of sensors for a robot in a specific job task. | | |
| 5 | The applications of robotics in industry. | | |
| Pre-requisites: | : Engineering mechanics, Basic Electrical & Electronics, Sensor & | Instrumentation | |
| | Course Contents / Sylla | abus | |
| UNIT-I | Introduction | | 8 hours |
| | of Robots, Advantages and Disadvantages of Robots, Robot Cor | | |
| | obot Reference Frames, Programming Modes, Robot Characteristic | cs, Robot Workspace, Robot Lang | <u> </u> |
| UNIT-II | Kinematics of Robots | | 8 hours |
| | vsis - Introduction, Robots as Mechanisms, Conventions, Matr | | |
| _ | of Transformations Forward and Inverse Kinematics of Robots, Fo | orward and Inverse Kinematics of | |
| UNIT-III | Actuators and Drive Systems | | 8 hours |
| Introduction, C | Characteristics of Actuating Systems, Comparison of Actuating S | Systems, Hydraulic Actuators, P | neumatic Devices Electric |
| | O 1 0 T 1 1 T T T T T T T T T T T T T T T | | |
| Motors, Micro | processor Control of Electric Motors, Pulse Width Modulation, | | |
| Motors, Microp Reduction | | | s with an H-Bridge, Speed |
| Motors, Microp Reduction UNIT-IV | Sensors | Direction Control of DC Motors | s with an H-Bridge, Speed 8 hours |
| Motors, Micror Reduction UNIT-IV Introduction, Se | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocity | Direction Control of DC Motors ty Sensors, Acceleration Sensors, 1 | s with an H-Bridge, Speed 8 hours Force and Pressure Sensors, |
| Motors, Microp Reduction UNIT-IV Introduction, So Torque Sensors | Sensors | Direction Control of DC Motors ty Sensors, Acceleration Sensors, 1 | s with an H-Bridge, Speed 8 hours Force and Pressure Sensors, |
| Motors, Micror Reduction UNIT-IV Introduction, So Torque Sensors | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocitys, Micro-switches, Visible Light and Infrared Sensors, Touch an | Direction Control of DC Motors ty Sensors, Acceleration Sensors, 1 | 8 hours Force and Pressure Sensors, nsors, Range Finders, Sniff |
| Motors, Micror Reduction UNIT-IV Introduction, Sor Torque Sensors Sensors UNIT-V | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocitys, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications | Direction Control of DC Motors ty Sensors, Acceleration Sensors, and Tactile Sensors, Proximity Sen | 8 hours Force and Pressure Sensors, nsors, Range Finders, Sniff 8 hours |
| Motors, Micror Reduction UNIT-IV Introduction, So Torque Sensors Sensors UNIT-V Robotics applie | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocitys, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications cations in Manufacturing-Material transfer and machine loading/ | Direction Control of DC Motors ty Sensors, Acceleration Sensors, ad Tactile Sensors, Proximity Sen /unloading, Processing operations | 8 hours Force and Pressure Sensors, nsors, Range Finders, Sniff 8 hours |
| Motors, Microp Reduction UNIT-IV Introduction, So Torque Sensors Sensors UNIT-V Robotics applie Assembly operation | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocitys, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications | Direction Control of DC Motors ty Sensors, Acceleration Sensors, ad Tactile Sensors, Proximity Sen /unloading, Processing operations | 8 hours Force and Pressure Sensors, nsors, Range Finders, Sniff 8 hours |
| Motors, Microp Reduction UNIT-IV Introduction, So Torque Sensors Sensors UNIT-V Robotics applie Assembly operation | Sensors ensor Characteristics, Sensor Utilization, Position Sensors, Velocitys, Micro-switches, Visible Light and Infrared Sensors, Touch an Robotics Applications cations in Manufacturing-Material transfer and machine loading/ations, Inspection automation. Limitation of usage of robots in processing processing sensors. | Direction Control of DC Motors ty Sensors, Acceleration Sensors, ad Tactile Sensors, Proximity Sen /unloading, Processing operations | 8 hours Force and Pressure Sensors, nsors, Range Finders, Sniff 8 hours |

| CO 3 | Interpret the various types of actuators and drive systems. | K4, K6 | |
|----------------|--|--------|--|
| CO 4 | CO 4 Explain the different type's sensor for a robot in a specific job task. K4, K5 | | |
| CO 5 | 5 Describe the applications of robotics in industry. K1, K3 | | |
| Text books | | | |
| 1. Saeed B. | Niku, "Introduction to Robotics – Analysis, Systems and Application": PHI 2006 | | |
| 2. J.J. Craig | g, Robotics, Addison-Wesley, 1986. | | |
| 3. K.S Fu, | R.C. Gonzalez, C.S.G. Lee, Robotics, McGraw Hill, 1987. | | |
| Reference Book | KS | | |
| | 1. An Introduction to Robot Technology, by CoifetChirroza, Kogan Page. | | |
| 2. Robotic | Engineering - An Integrated Approach: Richard D. Klafter Thomas A. | | |
| 3. Robotics | for Engineers, by Y. Koren, McGraw Hill. | | |
| NPTEL/ Youtu | be/ Faculty Video Link: | | |
| Unit 1 | Unit 1 https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1FkgPhpH&index=2 | | |
| Unit 2 | | | |
| Unit 3 | | | |
| Unit 4 | | | |
| Unit 5 | https://youtu.be/pSEjWxqE3R0 | | |

| | Bachelor of Technology Third Year | | |
|--|---|-------------------------------|---|
| Course Code | AEC0516 | LTP | Credits |
| Course Title | Machine Learning | 300 | 3 |
| Course Objectives: Stud | dent will learn about | · | |
| 1 | The machine learning and basics of statistics and probability theorem. | îy. | |
| 2 | Neurons, neural networks, and multilayer perceptron. | | |
| 3 | Identification of the dimensionality of data and its reduction using various mathematical concepts as well as probabilistic learning. | | |
| 4 | Various search and optimization techniques to the raw data. | | |
| 5 | Various learning techniques and approaches. | | |
| Pre-requisites: Basics of | f mathematics and python programming | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Introduction | | 8 Hours |
| TVITILIVALIATE KEPTESSION. | | | |
| Multivariate Regression. | Artificial Neural Network | | 0.11 |
| UNIT-II Neural Networks: Hebb separability, Linear Regr | Artificial Neural Network o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. | | , , |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amou | | rons, The Perceptron, Linear |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amount enetwork output and errors, Requirements of activation function. | | rons, The Perceptron, Linear |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amou | | rons, The Perceptron, Linear |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. The UNIT-III Dimensionality Reduct analysis, locally linear en | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amouse network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis and the Models, Nearest Neighbour methods. Support Vector Machine | nt of training d | rons, The Perceptron, Linear ata, number of hidden layers, 8 Hours vsis, Independent Component |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. The UNIT-III Dimensionality Reduct analysis, locally linear en Models: Gaussian Matri | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amouse network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis and the Models, Nearest Neighbour methods. Support Vector Machine | nt of training d | rons, The Perceptron, Linear ata, number of hidden layers, 8 Hours vsis, Independent Component |
| UNIT-II Neural Networks: Hebb separability, Linear Regr The Multi-layer Percep when to stop training. The UNIT-III Dimensionality Reduct analysis, locally linear en Models: Gaussian Matrialgorithm, Extensions of UNIT-IV Optimization and Sear climbing. | o's Rule, McCulloch and Pitts Neurons, Limitation of McCulloch ession, Back propagation algorithm. tron (MLP): MLP algorithm, Sequential and Batch training, Amouse network output and errors, Requirements of activation function. Dimensionality Reduction and Models ion: Linear discriminant analysis, Principal Component analysis and bedding, ISOMAP ix Models, Nearest Neighbour methods. Support Vector Machine SVM. | s, Factor analy (SVM): Optine | rons, The Perceptron, Linear ata, number of hidden layers, 8 Hours vsis, Independent Component and separation, Kernels, SVM 8 Hours e search, Greedy search, hill |

Reinforcement Learning: State and action spaces, the reward function, Markov chain decision process, Uses of Reinforcement Learning.

Learning with tree: Decision Tree, Classification and regression tree, Random Forest.

Unsupervised Learning: The k-means algorithm, Vector quantization, The self-organization feature map, Simulated annealing.

Course Outcomes: After completion of this course, students will be able to

| CO 1 | Describe the basic concepts of machine learning, statistics, and probability theory. | K1 |
|------|--|--------|
| CO 2 | Define and describe the Neurons, neural networks, and multilayer perceptron. | К3 |
| CO 3 | Identify the dimensionality of data and reduces it using various mathematical concepts as well as describe the probabilistic learning. | K3, K4 |
| CO 4 | Describe and apply various search and optimization techniques to the raw data. | K5 |
| CO 5 | Illustrate and apply various learning techniques. | K2 |

Text Books:

- 1. Stephen Marsland, "Machine Learing- An Algorithm Perspective", CRC Press, 2nd edition.
- 2. EthemAlpaydin, —Introduction to Machine Learning (Adaptive Computation and Machine Learning), The MIT Press 2004.
- 3. SimanHaykin, "Neural Netowrks", Prentice Hall of India
- 4. D.E. Goldberg, "Genetic Algorithms: Search, Optimization and Machine Learning", Addison Wesley

Reference Books:

- 1. Kumar Satish, "Neural Networks", Tata Mc Graw Hill
- 2. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", Wiley India.
- 3. Bishop, C., Pattern Recognition and Machine Learning. Berlin: Springer-Verlag.
- 4. An Introduction to Genetic Algorithms, Melanie Mitchell, MIT Press, 2000.

NPTEL/ Youtube/ Faculty Video Link:

| Unit 1 | https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC |
|--------|---|
| Unit 2 | https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC |
| Unit 3 | https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC |
| Unit 4 | https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC |

| Unit 5 | https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiHC |
|--------|---|
| | |

| | Bachelor of Technology Third Year | | | | |
|---|--|-------|--------|--|--|
| Course Code | AEC0551 L. | ΤP | Credit | | |
| Course Title | Control System Lab 0 | 0 2 | 1 | | |
| Course Objectives: Th | e student will learn about Application of MATLAB in Control System. | | | | |
| 1. | | | | | |
| 2. Analysis and plotting various pole-zero configuration in s-plane using MATLAB. | | | | | |
| 3. | The basics concept of time domain analysis and steady state error. | | | | |
| 4. | | | | | |
| 5. | The fundamental concept of steady state analysis and discrete control s | syste | m | | |
| | List of Experiments | | | | |
| Sr. No. | Name of Experiment | | CO | | |
| 1 | Introduction to MATLAB and Control System Toolbox. | | CO1 | | |
| 2 | Plot the pole-zero configuration in s-plane for the given transfer function $H(s) = \frac{2s+1}{s^2+5s+5}$ | | CO1 | | |
| 3 | Determine the transfer function for given closed loop system in block diagram representation. $R(s) + $ | | CO2 | | |
| 4 | A unity feedback control system has forward path transfer function is given below, determine time response for unit step input, rise time maximum overshoot. | | CO3 | | |

| | s+2 | |
|---|---|-----|
| | $G(s) = \frac{s+2}{s(s+1)}$ | |
| | The open loop transfer function of unity feedback control system is | CO3 |
| | given below find the position error coefficient, velocity error | |
| 5 | coefficient and acceleration error coefficient. | |
| | 10 | |
| | $G(s) = \frac{10}{(s^2 + 6s + 10)}$ | |
| | Determine gain margin phase margin and closed loop stability by | CO4 |
| | using Bode plot. Transfer function is given below | |
| | 4 | |
| 6 | $G(s)H(s) = \frac{4}{s(0.5s+1)(0.08s+1)}$ | |
| | 3(0.55 + 1)(0.005 + 1) | |
| | | |
| | Draw the Nyquist plot for open loop transfer function given below and | CO4 |
| 7 | comment on its closed loop stability. | |
| | 2.2 | |
| / | $G(s)H(s) = \frac{2.2}{s(s+1)(s^2+2s+2)}$ | |
| | 3(3 1)(3 23 2) | |
| | | |
| | Plot the root locus plot for the system when the open loop transfer | CO4 |
| 8 | function is given by | |
| | $G(s) = \frac{K}{s(s+4)(s^2+4s+13)}$ | |
| | | CO5 |
| | Obtain the state model for the transfer function given below | COS |
| 9 | C(s) $s+2$ | |
| | $\frac{C(s)}{R(s)} = \frac{s+2}{(s+3)(s+1)}$ | |
| | N(s) = (s + s)(s + 1) | |

| | The forward-path transfer function of a unity-feedback discrete-data control system with sample-and-hold is | CO5 |
|------------------------|--|------------|
| 10 | $G_{ho}G(z) = \frac{0.0952z}{(z-1)(z-0.905)}$ | |
| | The sampling period is $T=0.1$ s. (a) Plot the plot of $G_{ho}G(z)$ and determine the stability of the closed-loop system. | |
| | (b) Apply the w-transformation to $G_{ho}G(z)$ and plot the Bode plot of $G_{ho}G(w)$. Find the gain and phase margins of the system. | |
| Course Outcomes: After | Blooms Level | |
| CO 1 | Classify different tools in MATLAB. | K1, K2, K3 |
| CO 2 | CO 2 Evaluate the poles and zeros on s-plane along with transfer function of | |
| | a given system. | |
| CO 3 | Evaluate the various specifications of time domain response of a given system. | K1, K3, K4 |
| CO 4 | Examine the stability of a given transfer function using various | K1, K2, K3 |
| | methods such as Bode plot, Nyquist plot and root locus. | |
| CO 5 | Examine the concept of state variable analysis and discrete control | K2, K3, K4 |
| | system | |

| | Bachelor of Te | chnology Third Year | |
|----------|---|--|---------------------------------|
| Course | AEC0552 | LTP | Credit |
| Code | | 2.7. | |
| Course | CMOS Digital Integrated Circuit Lab | 0 0 2 | 1 |
| Title | | | - |
| | Objectives: The student will learn | | |
| L . | 1. VLSI EDA Tool. | | |
| 2. | Designing of various Logic gates. | | |
| 3. | Analyze CMOS Inverter and Voltage Follower. | | |
| 4. | Analysis and verification of CMOS Combinational Circuits. | | |
| 5. | Analysis and verification of CMOS Sequential Circuits. | | |
| <u> </u> | List of | Experiments | |
| Sr. | Name of Exp | eriment | CO |
| No. | • | | |
| 1 | Introduction to VLSI Basic and EDA Tools such as Microwind and or Siemens. | | CO1 |
| 2 | To design a 2-input NAND logic gate using 0.18 μm technologic | CO1 | |
| 3 | To design a 2-input NAND logic gate using 0.18 µm technologic | | CO2 |
| 4 | To design a 2-input NOR logic gate using 0.18 μm technolog | y and study its Transient characteristics. | CO2 |
| 5 | To design a NMOS source amplifier using 0.18 μm technolog | | CO2 |
| 6 | To design a voltage follower using 0.18 µm technology and s | • | CO2 |
| 7 | To design a CMOS inverter using 0.18 µm technology and str | | CO3 |
| 8 | To design and study the characteristic of CMOS XOR gate using 0.18 µm technology. | | CO4 |
| 9 | To design and study the characteristic of CMOS D flipflop using 0.18 µm technology. | | CO3 |
| | To design and study the characteristic of CMOS T flipflop using 0.18 μm technology. | | CO5 |
| | Course Outcome: After successful completion of this Lab students will be able to | | Blooms Level |
| CO 1 | Demonstrate VLSI EDA Tool. | | K ₃ |
| CO 2 | Design various Logic gates. | | K ₃ , K ₄ |
| CO 3 | 3 Analyze CMOS Inverter and Voltage Follower. | | K_3, K_4 |
| CO 4 | Analyze and verify CMOS Combinational Circuits. | | K ₂ |
| CO5 | CO5 Analyze and verify CMOS Sequential Circuits. | | |

| Bachelor of Technology Third Year | | | | |
|-----------------------------------|---|--|-----------------------|--|
| Course Code | AEC0511P | LTP | Credits | |
| Course Title | | 0 0 2 | 1 | |
| Course Object | Course Objectives: Student will learn about | | | |
| 1 | The interfacing of Bluetooth with Arduino and publishing of | data to the cloud. | | |
| 2 | 2 The connection of Node MCU and Thing speak cloud. | | | |
| | The controlling of LED, Home appliances with Node MCU, Raspberry Pi and blink app. | | | |
| | 4 The connection of temperature and humidity sensor with Node MCU and blink app. | | | |
| 5 | The detection of virgular motion and observation of various | s parameters of agricultural land. | | |
| Pre-requisites | s: Basic Knowledge of computer | | | |
| • | Course Contents / Syllab | | CO | |
| usingBlu | | OFFwhenmessageisreceivedfromSmartPhone | CO1 | |
| 2 To publi | shArduinodatatothecloud. | | CO1 | |
| | nect Node MCU with wi-fi Hotspots and sending Data to Thir | ng speak Server using Node MCU. | CO2, CO3 | |
| | rol the LED with Node MCU using Blink App. | | CO3 | |
| 5 To contr | ol home appliances using Node MCU using Blink App. | | CO2 | |
| | ol home appliances using Raspberry Pi 3 and MQTT. | | CO2, CO5 | |
| | ol the servo motor rotation using Node MCU and Blink App. | | CO2, CO4 CO2, CO4, | |
| 8 To read | To read the temperature and humidity using DHT11using Node MCU and Blink App. | | | |
| 9 To detec | t the virgular motion for home security system using Node M | ACU and Blink App. | CO2, CO5 | |
| | | | CO1, CO2 | |
| Course Outco | omes: After completion of this course students will be able | e to | | |
| CO 1 | The interfacing of Bluetooth devices with Arduino and applications, publication of data on cloud. | d its K1, K2 | | |
| CO 2 | Analyze Thing speak cloud and blink app. | K3 | | |
| CO 3 | Pi and blink app. | | | |
| CO 4 | Understand the function of DHT11 with Node MCU and b app. | n of DHT11 with Node MCU and blink K5 | | |
| CO 5 | | | | |

| | Bachelor of Technology Third Year | | | | | |
|------|-----------------------------------|---|------------------|--|--|--|
| Cou | rse Code | AEC0512P LTP | Credit | | | |
| Cou | rse Title | Embedded System Design Lab 0 0 2 | 1 | | | |
| Cou | rse Objecti | ves: Student will learn about | | | | |
| | 1 | Writing different programs for Arm based microcontroller. | | | | |
| | 2 | Freedom KL25Z board to build a system. | | | | |
| | 3 | Arm-based embedded system, and program to satisfy given user specifications. | | | | |
| | 4 | Commercial tools to develop Arm-based embedded systems. | | | | |
| | 5 | Commercial API and tools to accelerate the development cycle of Arm-based embedded systems. | | | | |
| Pre- | requisites: | Microcontrollers & Basics of Embedded system | | | | |
| | | Course Contents / Syllabus | CO | | | |
| 1 | | program to examine the assembly language program output of the compiler and the map file output of the linker. | CO1 | | | |
| 2 | | Thumb code to multiply the two 32-bit in memory at addresses $0x1234_5678$ and $0x7894_5612$, storing the result $0x2000_0010$. | CO1 | | | |
| 3 | | compile assembly code and debug the program image on an mbed board (namely the Freedom KL25Z board) Keil MDK-ARM tool. | CO2, CO3 | | | |
| 4 | C | | | | | |
| 5 | , i i | | | | | |
| 6 | Write a pr | ogram to implement an interrupt handler in a low-level. You are required to demonstrate the interrupt mechanism ches and LEDs on the board. | CO2, CO5 | | | |
| 7 | Write a pr | ogram to generate audio waves using the analogoutput, and use two potentiometers to tune the volume and pitch o. | CO2, CO4 | | | |
| 8 | of music u | ogram to design an audio player using the timer, PWM, and interrupts. The audio player will play a simple piece using the speaker, and display the melody of the music to the LEDs. Two potentiometers are used to adjust the ed and the volume respectively. | CO2, CO4, CO5 | | | |
| 9 | Write a pr | ogram to generate various signals using DAC which can be viewed on an oscilloscope or heard through a speaker. | CO2, CO5 | | | |
| 10 | | program and examine the assembly language program output of the compiler and the map file output of the | CO1, CO2 | | | |
| Cou | rse Outcon | nes: After completion of this course students will be able to | | | | |
| | CO 1 | Write a program for Arm based microcontroller. | K1 | | | |
| | CO 2 | Analyze Freedom KL25Z board to build a system. | K4 | | | |
| | CO 3 | Build an Arm-based embedded system, and program to satisfy given user specifications. | K3 | | | |
| | CO 4 | Use commercial tools to develop Arm-based embedded systems. | К3 | | | |

| | | | | В | ache | elor of | f Tec | hnolo | ogy T | hird | Year | | | | | | | | |
|-----------|--|----------|---------|---------|--------|---------|--------|--------|---------|---------|--------|----------|------|---------|-------|--------|-------|--------|------------|
| Course C | ode | AEC | 0513P | | | | | | | | | | L | TP | C | redit | | | |
| Course Ti | tle | Imag | ge Proc | essin | g an | d Patt | tern] | Reco | gniti | on La | ab | | 0 | 02 | | | | 1 | |
| Course O | bjectives: The stu | | | | | | | | | | | | | | | | | | |
| 1. | Basic skills for | | | | | | | | | | | | | | | | | | |
| 2. | Basic concept of | | | | | | | | | ques. | | | | | | | | | |
| 3. | Basic concept of | | | | | | | inalys | sis. | | | | | | | | | | |
| 4. | Analyze the spa | | | | | | | | | | | | | | | | | | |
| 5. | The use of vari | ious er | hancen | nent a | and so | egmer | ntatio | n tec | hniqu | ies fo | r dev | elopin | g co | mpute | r vi | sion a | pplic | ation. | |
| | _ | | | | | | | | rimer | | | | | | | | | | |
| Sr. No. | | | | | | Name | | | | | | | | | | | | CO | |
| 1 | Write a program | ım usin | g MAT | LAB | Pyth | hon to | disp | lay gi | rey so | cale/c | olour | image | es. | | | | | CO | |
| 2 | Write a program | | g MAT | TLAB, | 3/Pyth | hon to | extra | act di | fferei | nt attı | ribute | s (i.e., | Geo | metri | cal a | and | | CO |)2 |
| 3 | texture) of an Image. Write a program using MATLAB/Python for Image Negation. CO2 | | | | | | | | | | | | | | | | | | |
| 4 | Write a program using MATLAB/Python for Power Law Transformation. CO2 CO2 | | | | | | | | | | | | | | | | | | |
| 5 | | | | | | | | | | | | | | | | | | | |
| | Write a program using MATLAB/Python for Histogram Mapping and Equalization. CO2 Write a program using MATLAB/Python for Image Smoothening and Sharpening. CO1 | | | | | | | | | | | | | | | | | | |
| 6 | | | | | | | | | | | | | | | D . | 1 . | | | |
| 7 | Write a program Operators. | ım usın | g MAT | LAB | 3/Pytr | hon to | or Edg | ge De | etectio | on usi | ing So | obel, F | rew | itt and | Ro | berts | | CO |) 1 |
| 8 | Write a program | ım usin | g MAT | LAB | 3/Pyth | hon fo | or Mo | rphol | logica | al Op | eratio | ns on | Bina | ry Im | ages | S. | | CO | D3 |
| 9 | Write a program | ım usin | g MAT | LAB | /Pyth | hon fo | or Pse | udo (| Color | ing. | | | | | | | | CO | D 5 |
| 10 | Write a program | ım usin | g MAT | LAB | 3/Pyth | hon fo | or the | segm | nentat | tion u | sing | waters | hed | transfo | orm | | | CO | D 3 |
| 11 | Write a program | m to e | iminate | e the l | high | freque | ency | comp | onen | ts of | an im | age. | | | | | | CO |) 5 |
| 12 | Write a program using MATI AP/Puthon to extract the image feetures for image segmentation COA | | | | | | | | | | | | | | | | | | |
| Course O | utcomes: After si | | | | | | | | | | | able t | 0 | | | | | | |
| CO 1 | Implement image sharpening and image enhancement algorithm. K3, K4 | | | | | | | | | | | | | | | | | | |
| CO 2 | Analyze the po | | | | _ | | | | - | | n tech | nique | s. | | | | | K2, K3 | 3 |
| CO 3 | Learn basic ski | ills for | image | segm | entat | tion an | nd im | age a | analys | sis. | | | | | | | | K1, K2 | 2 |

| CO 4 | Analyze the spatial/ texture features of image. | K2, K3, K4 | | |
|------|---|------------|--|--|
| CO 5 | Implement and evaluate different enhancement and segmentation techniques for developing | | | |
| | computer vision applications. | | | |

| | Bachelor of | Technology Third Year | | | |
|-----------------|--|--|-------------------|--|--|
| Course code | ANC0501 | LTP | Credits | | |
| Course title | se title Constitution of India, Law and Engineering 2 0 0 | | | | |
| Course Objec | tives: In this course, the student will: | | | | |
| 1 | Learn the legacies of constitutional development of India and philosophy behind it. | in India and understand the most diversified legal document | K_1, K_2 | | |
| 2 | Aware of the theoretical and functional aspects of the Indian Parliamentary System. K ₁ | | | | |
| 3 | Understand the legal concepts and its implications | s for engineers. | K2 | | |
| 4 | Learn the law of intellectual property rights. K ₁ | | | | |
| 5 | 5 Learn the role of engineering in business organizations and e-governance. K ₁ | | | | |
| Pre-requisites | : Political science | | | | |
| | | | | | |
| | Course | Contents / Syllabus | | | |
| UNIT-I | NIT-I Introduction and Basic Information about Indian Constitution 6 hours | | | | |
| Meaning of th | e constitution law and constitutionalism, Historica | Background of the Constituent Assembly, Government of l | India Act of 1935 | | |
| and Indian In | dependence Act of 1947, Enforcement of the Con | stitution, Indian Constitution and its Salient Features, The | Preamble of the | | |
| Constitution, 1 | Fundamental Rights, Fundamental Duties, Directiv | ve Principles of State Policy, Parliamentary System, Federal | System, Centre- | | |
| | | | | | |

State Relations, Amendment of the Constitutional Powers and Procedure, The historical perspectives of the constitutional amendments in India, Emergency Provisions: National Emergency, President Rule, Financial Emergency, and Local Self Government – Constitutional Scheme in India.

UNIT-II Union Executive and State Executive 6 hours

Powers of Indian Parliament Functions of Rajya Sabha, Functions of Lok Sabha, Powers and Functions of the President, Comparison of powers of Indian President with the United States, **Powers and Functions of Vice-President**, Powers and Functions of the Prime Minister, Judiciary – The Independence of the Supreme Court, Appointment of Judges, Judicial Review, Public Interest Litigation, Judicial Activism, LokPal, Lok Ayukta, The Lokpal and Lok ayuktas Act 2013, State Executives – Powers and Functions of the Governor, Powers and Functions of the Chief Minister, Functions of State Cabinet, Functions of State Legislature, Functions of High Court and Subordinate Courts.

| UNIT-III | Introduction and Basic Information about Legal System: | 4 hours |
|-----------------|--|---------|
| Th. I 1 C | 4 C | I C |

The Legal System: Sources of Law and the Court Structure: Enacted law -Acts of Parliament are of primary legislation, Common Law or Case

law, Principles taken from decisions of judges constitute binding legal rules. The Court System in India and Foreign Courtiers (District Court, District Consumer Forum, Tribunals, High Courts, Supreme Court). Arbitration: As an alternative to resolving disputes in the normal courts, parties who are in dispute can agree that this will instead be referred to arbitration. Contract law, Tort, Law at workplace.

UNIT-IV Intellectual Property Laws and Regulation to Information

4 hours

Intellectual Property Laws: Introduction, Legal Aspects of Patents, Filing of Patent Applications, Rights from Patents, Infringement of Patents, Copyright and its Ownership, Infringement of Copyright, Civil Remedies for Infringement, Regulation to Information- Introduction, Right to Information Act, 2005, Information Technology Act, 2000, Electronic Governance, Secure Electronic Records and Digital Signatures, Digital Signature Certificates, Cyber Regulations Appellate Tribunal, Offences, Limitations of the Information Technology Act.

UNIT-V Business Organizations and E-Governance:

4 hours

Sole Traders, Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of Association, Articles of Association, Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up.

E-Governance and role of engineers in E-Governance, Need for reformed engineering serving at the Union and State level, Role of I.T. professionals in Judiciary, Problem of Alienation and Secessionism in few states creating hurdles in Industrial development.

Course outcome: After completion of this course students will be able to

| CO 1 | Identify and explore the basic features and modalities about Indian constitution. | K1 |
|------|--|--------|
| CO 2 | Differentiate and relate the functioning of Indian parliamentary system at the center and state level. | K2, K3 |
| CO 3 | Differentiate different aspects of Indian Legal System and its related bodies. | K2 |
| CO 4 | Discover and apply different laws and regulations related to engineering practices. | K3 |
| CO 5 | Correlate role of engineers with different organizations and governance models | K4 |

Text books

- 1. M Laxmikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill.
- 2. Brij Kishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.
- 3. Prabudh Ganguli: Gearing up for Patents: The Indian Scenario, Orient Longman.

Reference Books

- 1. BL Wadehra: Patents, Trademarks, Designs and Geological Indication Universal Law Publishing LexisNexis.
- 2. Executive programme study material Company Law, Module II, by ICSI (The Institute of Companies Secretaries of India) (Only relevant sections i.e., Study 1, 4 and https://www.icsi.edu/media/webmodules/publications/Company%20Law.pdf
- 3. Handbook on e-Governance Project Lifecycle, Department of Electronics & Information Technology, Government of India, https://www.meity.gov.in/writereaddata/files/eGovernance_Project_Lifecycle_Participant_Handbook-5Day_CourseV1_20412.pdf

Links

| Unit 1 | https://legalaffairs.nalsar.ac.in/students/student/course-details/1 |
|--------|---|
| Unit 2 | https://www.youtube.com/watch?v=1Z2tvimrLRQ&t=281s |
| Unit 3 | https://www.youtube.com/watch?v=H0_olSSX6D8&t=2s |
| Unit 4 | https://www.youtube.com/watch?v=WvduZOWoft0 |
| Unit 5 | https://www.youtube.com/watch?v=7SmrFh88Cuk |

| B. TECH. THIRD YEAR | | | | | |
|---------------------|---|-------|---------|--|--|
| Course code | ANC0502 | L T P | Credits | | |
| Course Title | ESSENCE OF INDIAN TRADITIONAL KNOWLEDGE | 2 0 0 | 2 | | |

Course objective: This course aims to provide basic knowledge about different theories of society, state and polity in India, Indian literature, culture, Indian religion, philosophy, science, management, cultural heritage and different arts in India.s

Pre-requisites: Computer Organization and Architecture

Course Contents / Syllabus

| | | J |
|--------|-----------------------------------|---------|
| UNIT-I | SOCIETY STATE AND POLITY IN INDIA | 8 Hours |

State in Ancient India: Evolutionary Theory, Force Theory, Mystical Theory Contract Theory, Stages of State Formation in Ancient India, Kingship, Council of Ministers Administration Political Ideals in Ancient India Conditions' of the Welfare of Societies, The Seven Limbs of the State, Society in Ancient India, Purusārtha, Varnāshrama System, Āshrama or the Stages of Life, Marriage, Understanding Gender as a social category, The representation of Women in Historical traditions, Challenges faced by Women.

| UNIT-II INDIAN LITERATURE, CULTURE, TRADITION, AND PRACTICES | 8 Hours |
|--|---------|
|--|---------|

Evolution of script and languages in India: Harappan Script and Brahmi Script. The Vedas, the Upanishads, the Ramayana and the Mahabharata, Puranas, Buddhist And Jain Literature in Pali,Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sanskrit Authors, Telugu Literature, Kannada Literature,Malayalam Literature ,Sangama Literature Northern Indian Languages & Literature, Persian And Urdu ,Hindi Literature

UNIT-III INDIAN RELIGION, PHILOSOPHY, AND PRACTICES

8 Hours

Pre-Vedic and Vedic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophical Doctrines, Other Heterodox Sects, Bhakti Movement, Sufi movement, Socio religious reform movement of 19th century, Modern religious practices.

UNIT-IV SCIENCE, MANAGEMENT AND INDIAN KNOWLEDGE SYSTEM 8 Hours

Astronomy in India, Chemistry in India, Mathematics in India, Physics in India, Agriculture in India, Medicine in India, Metallurgy in India, Geography, Biology, Harappan Technologies, Water Management in India, Textile Technology in India, Writing Technology in India Pyrotechnics in India Trade in Ancient India/,India's Dominance up to Pre-colonial Times.

UNIT-V CULTURAL HERITAGE AND PERFORMING ARTS

8 Hours

Indian Architect, Engineering and Architecture in Ancient India, Sculptures, Pottery, Painting, Indian Handicraft, UNESCO'S List of World Heritage sites in India, Seals, coins, Puppetry, Dance, Music, Theatre, drama, Martial Arts Traditions, Fairs and Festivals, UNESCO'S List of Intangible Cultural Heritage, Calenders, Current developments in Arts and Cultural, Indian's Cultural Contribution to the World. Indian Cinema.

COURSE OUTCOMES: After completion of this course students will be able to

| CO 1 | Understand the basics of past Indian politics and state polity. | K2 |
|------|---|----|
| CO 2 | Understand the Vedas, Upanishads, languages & literature of Indian society. | K2 |
| CO 3 | Know the different religions and religious movements in India. | K4 |
| CO 4 | Identify and explore the basic knowledge about the ancient history of Indian agriculture, science & technology, and ayurveda. | K4 |
| CO 5 | Identify Indian dances, fairs & festivals, and cinema. | K1 |

Text Books:

- 1. Sivaramakrishna (Ed.), Cultural Heritage of India-Course Material, Bharatiya Vidya Bhavan, Mumbai, 5th Edition, 2014.
- 2. S. Baliyan, Indian Art and Culture, Oxford University Press, India
- 3. Nitin Singhania, Indian Art and Culture: for civil services and other competitive Examinations,3rd Edition,Mc Graw Hill

Reference Books:

UNIT-III

Design of FIR Digital Filter

- 1. Romila Thapar, Readings In Early Indian History Oxford University Press, India
- 2. Basham, A.L., The Wonder that was India (34th impression), New Delhi, Rupa & co.

| | Bachelor of Technology Third Year | | | | | | |
|---|---|--------------------|--|--|--|--|--|
| Course Code | | LTP | Credits | | | | |
| Course Title | Digital Signal Processing | 3 1 0 | 4 | | | | |
| Course Object | Course Objectives: The students will learn about | | | | | | |
| 1 | The concept of digital signal processing, DFT, FFT & filt | ering in the frequ | lency domain. | | | | |
| 2 | The designing of Digital IIR filter from analog filter using | g different mappi | ng techniques for processing of discrete time signals. | | | | |
| 3 | The designing of digital finite impulse response filters using various methods (windows, sampling etc.) & effect of finite word length in digital filter. | | | | | | |
| 4 | The different types of IIR & FIR filter structures and their | r implementation | s. | | | | |
| 5 | The concept of multirate digital signal processing for vari | ous practical app | lications. | | | | |
| Pre-requisites | : Basic knowledge of signal & system | | | | | | |
| | Course Co. | ntents / Syllabus | 3 | | | | |
| UNIT-I | DFT and FFT | | 8 hours | | | | |
| Basics of signa | al processing, classification of signal processing, Application | ons of Digital Sig | nal Processing in real world. | | | | |
| Frequency An | nalysis of Discrete-Time Systems: Discrete Time Fourier | Transform (DTF | T), Discrete Fourier Transform (DFT), Properties of the DFT, | | | | |
| Relationship of | Relationship of DFT with DTFT & Z- transform. Linear Filtering using Circular Convolution and Linear Convolution. | | | | | | |
| Fast Fourier 7 | Fast Fourier Transform: Radix-2 DIT-FFT & DIF-FFT algorithm, inverse DFT using FFT algorithm. | | | | | | |
| UNIT-II Design of IIR Digital Filters 8 hours | | | | | | | |
| | Introduction to Filters, Classification of filter, Characteristic of digital filters, Filter Design Specifications. | | | | | | |
| Filter Transf | Filter Transformation Technique: Impulse Invariant Transformation, Bi-Linear Transformation, All- Pole Analog Filters: Butterworth and | | | | | | |
| Chebyshev, Analog frequency transformation, Design of Digital Butterworth, and Chebyshev Filters, digital frequency transformation. | | | | | | | |

8 hours

Linear phase FIR filter, frequency response of linear phase FIR filter, FIR filter Design using Fourier series method: Gibb's phenomenon, FIR filter Design using various window methods, Comparison of FIR & IIR digital filter.

Finite Word length effects in digital filters: Coefficient quantization error, Quantization noise – truncation and rounding, Limit cycle oscillations-dead band effects.

UNIT-IV Realization of Digital Systems

8 hours

Introduction- basic building blocks to represent a digital system, recursive and non-recursive systems, basic structures of a digital system: Canonical and Non-Canonical structures.

IIR Filter Realization: Direct form, Cascade, Parallel form realization, continued fraction expansion, Ladder structures.

FIR Filter Realization: Direct form, Cascade, FIR Linear Phase Realization.

UNIT-V Multirate Digital Signal Processing (MDSP)

8 hours

Introduction, Decimation, Interpolation, Sampling rate conversion: Single and Multistage, applications of MDSP- Sub-band Coding of Speech signals, Quadrature mirror filters, Advantages of MDSP.

Adaptive Filter: Introduction & Example of adaptive Filter, The window LMS Algorithm, Recursive Least Square Algorithm. The Forward-Backward Lattice and Gradient Adaptive Lattice Method.

Course Outcomes: After successful completion of the course students will be able to

| CO1 | Explain the concept of DFT & FFT and linear filtering using circular | K1, K2, K3, K5 |
|-----|--|----------------|
| | and linear convolution. | |
| CO2 | Design the digital IIR filters using various transformation techniques. | KI, K2, K4, K5 |
| CO3 | Design and analyse the FIR Filters and the effect of finite word length in digital filter. | K1, K2, K4, K5 |
| CO4 | Realize the digital system through different methods of realization structures and their utilities. | K1, K2, K4 |
| CO5 | Explain the concept of multirate digital signal processing, adaptive signal processing & basics of digital signal processor. | K1, K2, K3, K4 |

Textbooks

- 1. John G Prokias, Dimitris G Manolakis, "Digital signal processing Principles Algorithms & Applications", 4th edition, Pearson education, 2007.
- 2. Oppenheim & Schafer, "Discrete Time Signal Processing", Pearson education, Prentice Hall, 2nd edition, 2003
- 3. Johnny R. Johnson, "Digital Signal Processing", 3rd edition, PHI Learning pvtLtd., 2009

Reference Books

- 1. S.Salivahanan, "Digital signal processing", 6th edition, McGraw Hill Education pvt ltd.
- 2. Tarun K. Rawat, "Digital Signal Processing", 1st edition, Oxford University Press, 2015.
- 3. S.K. Mitra, 'Digital Signal Processing-A Computer Based Approach, McGraw Hill, 4th Edition.

| NPTEL/ YouTube/ Faculty Video Link: | | | |
|-------------------------------------|---|--|--|
| Unit 1 | • https://nptel.ac.in/courses/117105134/ | | |
| | http://www.digimat.in/nptel/courses/video/117105134/L38.html | | |
| Unit 2 | • <a 9wkva7jt2dw"="" href="https://ocw.mit.edu/resources/res-6-008-digital-signal-processing-spring-2011/video-lectures/lecture-15-design-of-iir-digital-filters-15-design-of-iir-dig</th></tr><tr><th></th><th><u>part-2/</u></th></tr><tr><th></th><th>• https://youtu.be/9WkvA7JT2dw | | |
| Unit 3 | • https://youtu.be/RJrEaTJuX_A | | |
| | • https://youtu.be/5ka_14DkoYQ | | |
| Unit 4 | • https://youtu.be/4Q-R1E5B40Q | | |
| | • https://youtu.be/9iE29uDpr0g | | |
| Unit 5 | https://youtu.be/HVGW85eGPQQ | | |
| | • https://youtu.be/XVMTpDK3UTk | | |

| Bachelor of Technology Third Year | | | |
|---|---|------------------------|--|
| Course Code | AEC0602 | LTP | Credits |
| Course Title | Wireless Communication Networks | 300 | 3 |
| Course Objectiv | ves: The student will be able to learn about | | |
| 1 | The basics of networking and various layers of models | | |
| 2 | The in-depth study and functions of layers. | | |
| 3 | The functioning of wireless communication systems and the estandards. | evolution o | f different wireless communication systems and |
| 4 | The cell architecture and advanced modulation used for wirele | ess commu | nication. |
| 5 | Multiple access techniques and design issues and security issu | ies associa | ted with Ad-hoc wireless networks. |
| Pre-requisites: 1 | Basic knowledge of communication and computer. | | |
| | Course Contents / S | · | |
| UNIT-I | Basics of Computer Network, Physical layer and Data Lin | | 8 hours |
| | /IP reference model, Understanding of Delay, Loss and Through | 1 ' | |
| · · | yer: guided transmission media, wireless transmission, the publ | | 1 2 |
| | er- Design issues, error detection and correction, elementary | data link _l | protocols, sliding window protocols, example data link |
| protocols – HDL | | | |
| UNIT-II | Network Layer, Transport Layer and Application Layer | | 8hours |
| Network Layer | -Virtual and Datagram networks, IP protocol and addressing | in the Inte | ernet the network layer in the internet (IPv4 and IPv6), |
| Subnetting with | IPs, Routing algorithms | | |
| Transport Laye | r - Multiplexing and Demultiplexing, UDP, Principles of reliable | e data trans | fer, TCP, Congestion control, SIP protocol. |
| Application La | yer- Web and HTTP, E-mail, DNS, Socket programming v | with TCP | and UDP. DNS, electronic mail, World Wide Web: |
| architectural ove | rview, dynamic web document and http. Application Layer Prote | ocols, Netv | vork Security. |
| UNI`T-III | Introduction to Wireless Communication | | 8hours |
| | 1G/2G/3G/4G Terminology. evolution of cellular systems in | | , , |
| | systems Fading, Requirements and Targets for Long Term Evo | lution (LT | E) - Technologies for LTE- 4G Advanced Features and |
| Roadmap Evolutions from LTE to LTEA - Wireless Standards. | | | |
| UNIT-IV | Cell Architecture and Modulation Technique | | 8hours |
| Small cells: Past, present, and future trends of cellular networks coverage and capacity of smallcell networks Interference management, D2D | | | |
| architecture Towards IoT Spectrum sharing. | | | |
| Multicarrier mod | lulation, OFDM, diversity multiplexing trade-off, OFDM syster | n, smart-a | ntenna: beam forming, cognitive radio, software-defined |

UNIT-VMultiple Access Techniques and Wireless Networks8hoursContention-free multiple access schemes (FDMA TDMA, CDMA, SDMA, and Hybrid), contention-based multiple access schemes (ALOHA and CSMA), Waveforms, Variable subcarrier spacing, supported transmission numerologies.

radio, communication relays, spectrum sharing.

UNIT-V

Design Challenges in Ad-hoc wireless networks, the concept of cross-layer design, security in wireless networks, energy-constrained networks, MANET and WSN.

Course Outcomes: After completion of this course students will be able to

| CO 1 | Analyze the requirements for a given organizational structure and select | K1, K4 |
|------|--|--------|
| | the most appropriate networking architecture and OSI Model. | |
| CO 2 | Analyze and design the topological and routing strategies for an IP | K4, K6 |
| | based networking infrastructure and explain the working knowledge of | |
| | computer applications and Network Security. | |
| | | |
| CO 3 | Explain the functioning of wireless communication systems and the | K2 |
| | evolution of different wireless communication systems and standards. | |
| CO 4 | Explain architecture and modulation technique used for wireless | K2 |
| | communication systems. | |
| CO 5 | Analyze the multiple access techniques and evaluate the design | K2 K5 |
| | challenges and security issues associated with Ad-hoc wireless networks. | |
| | | |

Text Books:

- 1. Computer Networks- A Top-Down approach, Behrouz Forouzan, McGraw Hill
- 2. T. S. Rappaport, R. W. Heath Jr., R. C. Daniels, and J. M. Murdock, Millimeter Wave Wireless Communication., Pearson Education, 2015.
- 3. Andrea Goldsmith, "Wireless Communications", Cambridge University Press, 2005.

Reference Books:

- 1. Computer Networks (4th edition), Andrew Tanenbaum, Prentice Hall
- 2. Vijay K Garg, "Wireless Communications and Networks", Morgan Kaufmann Publishers an Imprint of Elsevier, USA 2009 (Indian reprint)
- 3. Computer Networking and the Internet (5th edition), Fred Halsall, Addison Wesley.
- 4. Computer Networking- A Top-Down approach, 5th edition, Kurose and Ross, Pearson.

| Unit 1 | https://nptel.ac.in/courses/106/105/106105183/ |
|--------|---|
| | https://nptel.ac.in/courses/106/105/106105081/ |
| Unit 2 | https://swayam.gov.in/nd1_noc20_cs23/preview |
| | https://nptel.ac.in/courses/106105031 |
| Unit 3 | https://www.youtube.com/watch?v=f2wlHL1Sok8&list=PLuv3GM6-gsE3ypUYh43pPuZsXxJVG1e7F |
| Unit 4 | https://www.youtube.com/watch?v=AKXFwwcww_E |
| Unit 5 | https://www.youtube.com/watch?v=ycaz99NogS4&list=PLJ5C_6qdAvBHroAfekCO |

| | Bachelor of Technology Third Year | | |
|------------------------|--|-------|---------|
| Course Code | AEC0603 | LTP | Credits |
| Course Title | 5G Technology | 3 0 0 | 3 |
| Course Objecti | ves: The student will learn about | | |
| 1 | The basics of 5G architecture and protocols. | | |
| 2 | The propagation scenarios and channel modelling. | | |
| 3 | The 5G techniques i.e. massive MIMO and mm wave. | | |
| 4 | The mobility and handoff management in 5G. | | |
| 5 | The network slicing, Network Function Virtualization | | |
| Pre-requisites: | Wireless Communication | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Introduction to 5G Architecture and Protocols | | 8 hours |

Introduction to 5G RAN (Radio Access Networks), 5G NR Logical architectures, 5G NR Protocol stack (Layer 2 and Layer 3) **Introduction to Physical Layer:** Physical layer techniques, 5G NR MAC layer Architecture, functions, Channel Mapping, Procedures, Headers and Subheaders.

UNIT-II Propagation Scenarios and Channel Modelling 8 hours

Channel modelling requirements, propagation scenarios and challenges in the 5G modelling, Channel Models for mm Wave MIMO Systems. 5G Requirements, Key Capabilities of 5G versus 4G, 5G operating scenario, mm wave technology, Propagation modelling of 5G

UNIT-III Massive MIMO Techniques 8 hours

Massive MIMO propagation channel models, Channel Estimation in Massive MIMO, Massive MIMO with Imperfect CSI, Multi-Cell Massive MIMO, beamforming.

8 hours

UNIT-IV Mobility and Handoff Management

Interference and mobility management in 5G, Handoff management in 5G, QoS improvement with 5G, QoS mechanisms offered by 5G, 5G QoS Flow Descriptions and Characteristics.

IP Routing: Types of routing protocols, IPv6 addressing.

UNIT-V Network Slicing and Function Virtualization 8 hours

Network Slicing: Concept, architecture, the status of network slicing in 5G standards, network slicing in core networks, network slicing challenges for 5G Networks.

Network Functions Virtualization (NFV): Functionality, architecture, advantages for 5G network.

| Course Outcom | es: After successful completion of the course, the student will be able to: | Bloom's Level |
|---------------|---|-----------------------|
| CO 1 | Demonstrate Radio access network and protocol stack. | K ₃ |
| CO 2 | Analyze indoor and outdoor propagation models. | K ₄ |
| CO 3 | Apply massive MIMO technique in wireless communication. | K ₃ |
| CO 4 | Apply mobility management in heterogeneous and network-controlled handover. | K ₃ |
| CO 5 | Demonstrate the fundamentals of network slicing core networks. | K ₃ |

Text Books:

- 1. Martin Sauter "From GSM to LTE-Advanced Pro and 5G: An Introduction to Mobile Networks and Mobile Broadband", Wiley-Blackwell.
- 2. AfifOsseiran, Jose. F. Monserrat, Patrick Marsch, "Fundamentals of 5G Mobile Networks", Cambridge University Press. Radar Principles, Technology, Applications, Byron Edde, Pearson Education, 2004.
- 3. Athanasios G.Kanatos, Konstantina S.Nikita, Panagiotis Mathiopoulos, "New Directions in Wireless Communication Systems from Mobile to 5G", CRC Press.
- 4. Saad Asif, "5G Mobile Communications Concepts and Technologies", first edition, CRC Press.

Reference Books

- 1. Jonathan Rodriguez, "Fundamentals of 5G Mobile Networks", John Wiley &Sons.WHHayt and JA Buck, "Engineering Electromagnetic", 7th Edition TMH, 2013.
- 2. Theodore S.Rappaport, Robert W.Heath, Robert C.Danials, James N.Murdock "Millimeter Wave Wireless Communications", Prentice Hall Communications.

| Unit 1 | https://www.youtube.com/watch?v=aYJncUscfmk | |
|--------|---|--|
| Unit 2 | https://www.youtube.com/watch?v=khsqASfv2T4&list=PLxJYaXA6j4AbpWZmDztACJNA5vA3rvfM0&index=6 | |
| Unit 3 | https://www.youtube.com/watch?v=am3Zs8QpLLY | |
| Unit 4 | https://www.youtube.com/watch?v=q9Pk68iAHVA | |

| Ī | Unit 5 | https://www.youtube.com/watch?v=pUlfcGyFCFo | |
|---|--------|---|--|
| | | | |

| | Bachelor of Technology Third Year | | |
|---------------------|---|----------|---------|
| Course Code | AEC0611 | LTP | Credits |
| Course Title | Privacy and Security in IoT | 3 0 0 | 3 |
| Course Objectives: | Student will learn about | <u>'</u> | |
| 1 | The security requirements in IoT Architecture. | | |
| 2 | The basic concepts of cloud security and services. | | |
| 3 | The cryptographic primitives and its role in IoT. | | |
| 4 | The privacy and trust models for IoT. | | |
| 5 | The network security and its management. | | |
| Pre-requisites: Bas | ic fundamental of microprocessor, microcontroller & Embedded System | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Securing the Internet of Things | | 8 hours |

Security Requirements in IoT Architecture - Security in Enabling Technologies - Security Concerns in IoT Applications. Security Architecture in the Internet of Things - Security Requirements in IoT, Insufficient Authentication/Authorization - Insecure Access Control - Threats to Access Control, Privacy, and Availability, Attacks Specific to IoT. Vulnerabilities, Secrecy and Secret-Key Capacity Authentication/Authorization for Smart Devices, Transport Encryption, Attack & Fault trees

UNIT-II Cloud Security for IoT

8 hours

Cloud services and IoT, offerings related to IoT from cloud service providers, Cloud IoT security controls, An enterprise IoT cloud security architecture, New directions in cloud enabled IoT computing

UNIT-III Cryptographic Fundamentals for IoT

8 hours

Cryptographic primitives and its role in IoT, Encryption and Decryption, Hashes, Digital Signatures, Random number generation, Cipher suites, key management fundamentals, cryptographic controls built into IoT messaging and communication protocols, IoT Node Authentication

UNIT-IV Privacy Preservation and Trust Models For IoT

8 hours

Concerns in data dissemination – Lightweight and robust schemes for Privacy protection – Trust and Trust models for IoT – self-organizing Things - Preventing unauthorized access.

UNIT-V Network Security and Management

8 hours

Principles of cryptography, Authentication, integrity, key distribution and certification, Access control and Firewalls, attacks and counter measures, security in many layers. Infrastructure for network management, The internet standard management framework, SMI, MIB, SNMP, Security and administration.

| Course Outcomes: After completion of this course students will be able to | | | | |
|---|--|-----------|--|--|
| CO 1 | Explain security requirements in IoT Architecture. | K1, K2 | | |
| CO 2 | Realize the basic concepts of cloud security for IoT. | K1, K3 | | |
| CO 3 | Explain the cryptographic primitives and its role in IoT. | K1, K2 | | |
| CO 4 | Implement the various trust models for IoT. | K1, K4 | | |
| CO 5 | Realize the various types of network security and its management. | K1, K3 | | |
| 2. Cryptography Reference Books 1. Securing the l | rnet of Things Security (Kindle Edition) by Brian Russell, Drew Van Duren & Networks Security Stallings, William 3rd edition Internet of Things Elsevier | | | |
| 2. William Stall: NPTEL/ Youtube/ F | ings, "High-Speed Networks and Internets, Performance and Quality of Service", Pearson I Caculty Video Link: | Education | | |
| Unit 1 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=89&lesson=92 | | | |
| Unit 2 | https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=75&lesson=79 | | | |
| Unit 3 | https://www.youtube.com/watch?v=jSsehESW37c | | | |
| Unit 4 | Unit 4 https://www.youtube.com/watch?v=sMquG8gxRh4 | | | |
| Unit 5 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=41&lesson=42 | | | |

| | Bachelor of Technology Third Year | | |
|---|--|-------|---------|
| Course Code | AEC0612 | LTP | Credits |
| Course Title | Real Time Operating System | 3 0 0 | 3 |
| Course Objectives: Student will learn about | | | |
| 1 | Embedded OS internals. | | 1 |
| 2 | The basic concepts of Real Time Operating System. | | |
| 3 | Concepts of Process and Task Scheduling. | | |
| 4 | Strategies to interface memory and I/O with RTOS kernel. | | |
| 5 | Architecture of CMSIS-RTOS & process of RTX task management. | | |
| Pre-requisites: Bas | sic fundamental of microprocessor, microcontroller & Embedded System | | |
| | Course Contents / Syllabus | | |
| UNIT-I | Embedded of Internals | | 8 hours |

Linux internals: Process Management, File Management, Memory Management, I/O Management. Overview of POSIX APIs, Threads – Creation, Cancellation, POSIX Threads Inter Process Communication – Semaphore, Pipes, FIFO, Shared Memory Kernel: Structure, Kernel Module Programming Schedulers and types of scheduling. Interfacing: Serial, Parallel Interrupt Handling Linux Device Drivers: Character, USB, Block & Network.

UNIT-II Overview of RTOS 8 hours

OS overview: OS components, OS structure, Types of Operating Systems, Basics of RTOS: Real-time concepts, Characteristics of RTOS, Architecture of RTOS, Classification of RTOS: Hard Real time and Soft Real-time, Firm real time system, Advantage and disadvantage of RTOS.

UNIT-III Process and Scheduling 8 hours

Process: Introduction, Memory lay out of an executing program, Process control block, Process creation, Process Termination, Context Switching and States, RTX and Linux Examples.

Scheduling: Levels of scheduling of tasks, scheduling criteria, scheduling algorithms non-pre-emptive or pre-emptive. Quantum size of task, priority of task, Real Time Scheduling and aperiodic Real time scheduling.

| UNIT-IV | Concurrency and Memory Management | 8 hours |
|-------------------|--|------------------------------|
| | currency Scheduling, Multiprocessing environment, Read-write by multiple CPUs and consist | |
| | Hardware Mutex, Software Mutex, Example: Dekker's algorithm, Semaphore, Deadlock, Banke | _ |
| • | nent: Processes Need Memory, Address Binding & its types, Memory Hierarchy, Virtual M | Iemory, Memory Partitioning, |
| | on with Paging, File System, File Structure, Directory Structure, Disk, Interrupt & DMA. | |
| UNIT-V | RTX | 8 hours |
| T | X files, RTX task and time management, Simple Time Management APIs, Task Priority | |
| Communication, Ev | vent, Interrupt, Mutex, Semaphore, Mailboxes and Messages in RTX, RTX control functions, A | rchitecture of CMSIS-RTOS. |
| Course Outcomes: | After completion of this course students will be able to | |
| CO 1 | Explain Arm processor architectures. | K1, K2 |
| CO 2 | Realize the basic concepts of RTOS. | K1, K4 |
| CO 3 | Apply the concepts of Process and Task Scheduling. | K3 |
| CO 4 | Implement strategies to interface memory and I/O with RTOS kernel. | K2 |
| CO 5 | Analyze the architecture of CMSIS-RTOS & process of RTX task management. | K2, K4 |
| Text books | | |
| 1. Venkateswa | ranSreekrishnan," Essential Linux Device Drivers", Ist Kindle edition, Prentice Hall, 2008 | |
| 2. Jonathan W. | . Valvano, "Real-Time Operating Systems for ARM Cortex-M Microcontrollers" Jonathan Valv | vano; 4 edition. |
| Reference Books | | |
| 1. Jerry Coope | rstein, "Writing Linux Device Drivers: A Guide with Exercises", J. Cooperstein publishers ,200 |)9 |
| 2. Qing Li and | Carolyn Yao, "Real Time Concepts for Embedded Systems" – Qing Li, Elsevier ISBN:15782 | 01241 CMP Books © 2000 |
| NPTEL/ Youtube/ | Faculty Video Link: | |
| Unit 1 | https://www.youtube.com/channel/UCiwfpGavlOTzATgDSZJ62vA | |
| Unit 2 | https://www.youtube.com/channel/UCiwfpGavlOTzATgDSZJ62vA | |
| Unit 3 | https://www.youtube.com/watch?v=Lwa7n0G5OHc | |
| Unit 4 | https://www.youtube.com/watch?v=Qske3yZRW5I | |
| Unit 5 | https://www.youtube.com/watch?v=Q4qu4ADTy9Q | |

| | Bachelor of Technology Third Year | |
|--|--|--|
| Course Code | AEC0613 LTP | Credits |
| Course Title | ANN & Deep learning 300 | 3 |
| Course Object | ives: Student will learn about | |
| 1 | The basic principles and techniques of artificial neural network and deep learning. | |
| 2 | PCA, auto encoders, and other type of encoders. | |
| 3 | Choices and limitations of a model for a given setting. | |
| 4 | How to apply deep learning techniques to practical applications. | |
| 5 | RNN, GRU & LSTM and will also learn how to critically evaluate model performance and int | erpret results. |
| Pre-requisites Machine Learn | Working knowledge of Linear Algebra, Probability Theory. It would be beneficial if the parting. Course Contents / Syllabus | ticipants have done a course of |
| TINITE | | 8 Hours |
| Representation | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N | ultilayer Perceptron's (MLPs) etworks, Back propagation. |
| Introduction: I Representation UNIT-II Gradient Descripterpretations, | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto enc | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it |
| Introduction: I Representation UNIT-II Gradient Descinterpretations, Sparse auto encounters | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, McPower of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural Notember (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders |
| Introduction: I Representation UNIT-II Gradient Descripterpretations, | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto enc | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it |
| Introduction: Introduction: Interpretations and Interpretations, Sparse auto end UNIT-III Regularization: | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, McPower of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural Notember (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours |
| Introduction: Introduction: Interpretations and Interpretations, Sparse auto end UNIT-III Regularization: | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layer | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours |
| Introduction: Introduction: Introduction: Interpretation | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layer ation methods, Batch Normalization, Learning Vectorial Representations of Words. | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours wise Pre-training, Softmaxlayer |
| Introduction: Introduction: Introduction: Interpretation UNIT-II Gradient Descripter interpretations, Sparse auto end UNIT-III Regularization: weight initializ UNIT-IV | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layer ation methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours wise Pre-training, Softmaxlayer |
| Introduction: In Representation UNIT-II Gradient Descripter Descripter auto encounter auto enc | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layeration methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures Neural Networks, LeNet, AlexNet, ZF-Net, VGGNet, ResNet, DenseNet. RNN and LSTM models ral Networks, Back propagation through time (BPTT), Vanishing and Exploding Gradients, T | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours wise Pre-training, Softmaxlayers 8 Hours 8 Hours |
| Introduction: In Representation UNIT-II Gradient Descripter Descripter auto end UNIT-III Regularization: weight initializ UNIT-IV Convolutional In UNIT-V Recurrent Neurone Encoder Decoder | History of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, M Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Feed Forward Neural N Optimization & Dimensionality Reduction ent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Singular Value Decomposition, Auto encoders and relation to PCA, Regularization in auto encoders. Deep Learning Fundamentals Bias Variance Tradeoff, L2 regularization, Early stopping, Dataset augmentation, Greedy Layeration methods, Batch Normalization, Learning Vectorial Representations of Words. Deep learning architectures Neural Networks, LeNet, AlexNet, ZF-Net, VGGNet, ResNet, DenseNet. RNN and LSTM models ral Networks, Back propagation through time (BPTT), Vanishing and Exploding Gradients, T | ultilayer Perceptron's (MLPs) etworks, Back propagation. 8 Hours Component Analysis and it oders, Denoising auto encoders 8 Hours wise Pre-training, Softmaxlayers 8 Hours 8 Hours |

| CO 2 | Apply neural networks using various learning techniques and formulate the artificial neural network with different layers. | K3, K5 |
|------|--|--------|
| CO 3 | Describe deep neural networks (DNN) using various learning techniques and formulate DNN with different layers. | K3, K4 |
| CO 4 | Apply different architectures of deep learning and summarize the difference between them. | K5 |
| CO 5 | Apply different deep learning techniques to practical applications and evaluate their performance. | K2, K5 |

Text Books:

- 1. S. Rajsekaran& GA Vijayalakshmi Pai, "Neural Networks, Fuzzy Logic and Genetic Algorithm: Synthesis and Applications", Prentice Hall of India.
- 2. SimanHaykin, "Neural Netowrks", Prentice Hall of India
- 3. Ian Goodfellow and YoshuaBengio and Aaron Courville, Deep learning, MIT Press, 2016
- 4. Charu, C. Agrawal, Neural Networks and Deep Learning, Kindle edition, 2018

Reference Books:

- 1. Kumar Satish, "Neural Networks", Tata Mc Graw Hill
- 2. Machine Intelligence: Demystifying Machine Learning, Neural Networks and Deep Learning,
- 3. Notion Press, 2019
- 4. Bishop, Pattern Recognition and Machine Learning, Springer

| Unit 1 | https://www.youtube.com/watch?v=OBFZPivcdqg |
|--------|---|
| | https://www.youtube.com/watch?v=4TC5s_xNKSs |
| Unit 2 | https://www.youtube.com/watch?v=xbYgKoG4x2g |
| Unit 3 | https://www.youtube.com/watch?v=aPfkYu_qiF4 |
| Unit 4 | https://www.youtube.com/watch?v=wPz3MPl5jvY |
| Unit 5 | https://www.youtube.com/watch?v=9TFnjJkfqmA |

| | Bachelor of Technology Thi | ird Year | |
|--|--|--|--|
| Course Code | AEC0614 | LTP | Credits |
| Course Title | IoT Networks | 3 0 0 | 3 |
| Course Objectives | s: Student will learn about | | |
| 1 | The different types of networks and its requirement. | | |
| 2 | The principles behind the Modern Network approaches s | such as SDN NFV and IoT. | |
| 3 | The various components of IoT enabled things. | | |
| 4 | The basic concept of virtual machines and functions. | | |
| 5 | The various security requirements. | | |
| Pre-requisites: Ba | asics of IoT and its Protocols | | |
| | Course Contents / Sylla | abus | |
| UNIT-I | Modern Networking | | 8 hours |
| | | | |
| UNIT-II | Software Defined Networks | | 8 hours |
| Network Requirem Flow Protocol, SDI | nents, The SDN Approach, SDN and NFV Related Standards, SN Control Plane Architecture, REST API, SDN Application Plan | <u> </u> | Network Device, Open |
| Network Requirem Flow Protocol, SDI UNIT-III | nents, The SDN Approach, SDN and NFV Related Standards, SN Control Plane Architecture, REST API, SDN Application Plan IoT Components | ne Architecture | Network Device, Open |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop | nents, The SDN Approach, SDN and NFV Related Standards, SN Control Plane Architecture, REST API, SDN Application Plan | ne Architecture | Network Device, Open |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop | nents, The SDN Approach, SDN and NFV Related Standards, SN Control Plane Architecture, REST API, SDN Application Plan IoT Components e of the Internet of Things, Components of IoT-Enabled Thing | ne Architecture | Network Device, Open |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M | IoT Components e of the Internet of Things, Components of IoT-Enabled Things System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV References | ne Architecture | 8 hours el, ITU-T IoT Referenc |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M | Internation Inter | ne Architecture | 8 hours el, ITU-T IoT Referenc |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V | IoT Components e of the Internet of Things, Components of IoT-Enabled Thingsystem, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iot Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Refanagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security | es, IoT World Forum Reference Mod | 8 hours el, ITU-T IoT Referenc 8 hours ure, Virtualized Networ |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem | Internation Inter | es, IoT World Forum Reference Mod Ference Architecture, NFV Infrastruct , IoT Security, The Patching Vulner | 8 hours el, ITU-T IoT Reference 8 hours ure, Virtualized Network 8 hours ability, IoT Security and |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem Privacy Requireme | IoT Components e of the Internet of Things, Components of IoT-Enabled Things System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iot Security ents, SDN Security, NFV Security, ETSI Security Perspective, | es, IoT World Forum Reference Mod Ference Architecture, NFV Infrastruct , IoT Security, The Patching Vulner | 8 hours el, ITU-T IoT Reference 8 hours ure, Virtualized Networe 8 hours ability, IoT Security an |
| Network Requirem Flow Protocol, SDI UNIT-III The IoT Era, Scop Model, Cisco IoT S UNIT-IV Background and M Functions, NFV M UNIT-V Security Requirem Privacy Requireme | IoT Components e of the Internet of Things, Components of IoT-Enabled Things System, Io Bridge, SDN and NFV over IoT Deployment Virtualization Iotivation for NFV, Virtual Machines, NFV Concepts, NFV Refanagement and Orchestration, NFV Use Cases, SDN and NFV IoT Security ents, SDN Security, NFV Security, ETSI Security Perspective, ents Defined by ITU-T, An IoT Security Framework, The Impact | es, IoT World Forum Reference Modes Ference Architecture, NFV Infrastruct The John Security, The Patching Vulneration of the New Networking on IT Career | 8 hours el, ITU-T IoT Reference 8 hours ure, Virtualized Network 8 hours ability, IoT Security and |

| CO 3 | Describe the various components of IoT Enabled Things. | K1, K3 |
|------------------|--|----------------------------------|
| CO 4 | Explain the concept of virtual machines and their network functions. | K1, K3 |
| CO 5 | Describe the various requirements of security. | K2, K3 |
| | | |
| Text books | | |
| 1. "Foundations | of Modern Networking: SDN, NFV, QoE, IoT, and Cloud" William Stallings Publisher: Ad | ddison-Wesley 2015 |
| 2. SDN and NF | V Simplified: A Visual Guide to Understanding Software Defined Networks and Networks | work Function Virtualization 1st |
| Edition by Jin | n Doherty | |
| Reference Books | | |
| 1. Software Defi | ned Networks: A Comprehensive Approach, Ist Edition by Paul Goransson Chuck Black | |
| 2. Network Fund | tion virtualization with a touch of SDN by Paresh Shah, Syed Farrukh Hassan, Rajendra Cl | hayapathi |

| Unit 1 | https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=16 |
|--------|--|
| Unit 2 | https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=75&lesson=76 |
| Unit 3 | https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=53 |
| Unit 4 | https://www.youtube.com/watch?v=Vl5UJUR1uV4 |
| Unit 5 | https://www.business.att.com/learn/tech-advice/the-security-benefits-of-software-defined-networkingsdnhtml |
| | |

| | Bachelor of Technology Th | nird Year | |
|--------------------|--|--|------------------------|
| Course Code | AEC0615 | LTP | Credits |
| Course Title | Robotics Design Mechanism | 3 0 0 | 3 |
| Course Objective | s: Student will learn about | , | |
| 1 | Industrial robots and their operational workspace characteristics and their operational workspace characteristics. | cteristics & the tools taking part in the ma | nufacturing process. |
| 2 | Dynamic analysis of drives. | | |
| 3 | The feedback sensors its types & transporting devices. | | |
| 4 | The feeding materials used according to application & o | orientation. | |
| 5 | Functional systems & prototypes of robots. | | |
| Pre-requisites: In | ntroduction to Robotics & its Applications | | |
| | Course Contents / Syll | abus | |
| UNIT-I | Introduction | | 8 hours |
| Review and Defin | nitions: Robots & its Kinds, Definition of Levels, Manipulate | ors, Structure of Automatic Industrial S | ystems, Non-industria |
| • | the Robot Family, Relationship between the Level of Robot "Int | · · | |
| Concepts and La | youts: Processing Layout, Concept of an Automatic Manufac | eturing Process, Productivity of a Manus | facturing Process, The |
| Kinematic Layout, | Rapid Prototyping | | |
| UNIT-II | Dynamic Analysis of Drives | | 8 hours |
| | rive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, D | | |
| | Control of Automatic Machines: Position Function, Camshafts | | ic Accuracy, Dampin |
| of Harmful Vibrati | ions, Automatic Vibration Damping, Electrically Controlled Vibration | ration Dampers | |

UNIT-III Feedback Sensors 8 hours

Linear and Angular Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensors.

Transporting Devices: General Considerations, Linear Transportation, Rotational Transportation, Vibrational Transportation

| UNIT-IV | Feeding and Orientation Devices | 8 hours |
|---------------------------|--|----------------------|
| Introduction, Feeding of | Liquid and Granular Materials, Feeding of Strips, Rods, Wires, Ribbons, Feeding of Oriented Parts | s from Magazines, |
| Feeding of Parts from Bir | ns, General Discussion of Orientation of Parts, Passive Orientation, Active Orientation, Logical Orientation | ntation, Orientation |
| by Non-machanical Maan | | |

UNIT-V Functional Systems and Mechanisms 8 hours

| | automatic Assembling, Special Means of Assembly, Inspection Systems, Miscellaneous Mechanisms | |
|--------------------|--|-------------------|
| Manipulators: Dyna | amics of Manipulators, Grippers & Guides. | |
| Course Outcomes: | After completion of this course students will be able to | |
| CO 1 | Explain industrial robots and their operational workspace characteristics & Manipulators. | K1, K2 |
| CO 2 | Analyze drives & its control. | K2 |
| CO 3 | Describe the use of sensors & solve kinematics of robot manipulators. | K3 |
| CO 4 | Apply feed material & orientation. | K4, K5 |
| CO 5 | Create application based prototypes of robots. | K1, K3 |
| Text books | | |
| 3. Ben-Zion Sai | ndler: Robotics designing the mechanisms for automated machinery, Prentice-Hall | |
| 4. Pessen, D. W | :: Industrial Automation, John Wiley & Sons, New York | |
| Reference Books | | |
| 3. Schey, John | A., Introduction to Manufacturing Processes: Second Edition, McGraw-Hill International | |
| 4. Critchlow, A | rthur J., Introduction to Robotics, Macmillan Publishing Company, New York, Collier Macmillan Publ | lishers, Londo |
| NPTEL/ Youtube/ | Faculty Video Link: | |
| Unit 1 | https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1F | kgPhpH&index=2 |
| Unit 2 | https://www.youtube.com/watch?v=XOg1KT6xD04&list=PLyqSpQzTE6M_XM9cvjLLO_Azt | t1FkgPhpH&index=4 |
| Unit 3 | https://youtu.be/ksOgvhYdqX8 | |
| Unit 4 | https://youtu.be/Gc4BiUGiV-Q | |
| Unit 5 | https://youtu.be/pSEjWxqE3R0 | |

| | Bachelor of Technology Third Year | | |
|--------------------------|---|----------------|---------|
| CourseCode | AEC0616 | L TP | Credits |
| CourseTitle | ArtificialIntelligence | 300 | 3 |
| Course Objectives | Student will learn about | | |
| 1 | Historical perspective of AI and its foundations. | | |
| 2 | Principles of AI toward problem solving and drawing inference thereof. | | |
| 3 | Perception, knowledge representation, and different learning techniques. | | |
| 4 | Architecture of knowledge-Based System, Rule-based systems, and other ex- | xpert systems. | |
| 5 | Evolutionary computational algorithms and different search algorithms. | | |

Pre-requisites: BasicknowledgeofAlandMachine LearningConcepts.

CourseContents/ Syllabus

UNIT-I Introduction 8 Hours
Introduction to Artificial Intelligence, Historical developments of Artificial Intelligence, well defined learning problems, Designing a Learning

System, Basics of problem-solving: problem representation paradigms, statespace, satisfiability optimality, pattern classification problems, exampledomains.

UNIT-II SearchTechniques 8 Hours

Searching for solutions, Uninformed Search Strategies: DFS, BFS, Informed Search Strategies: Local searchalgorithms and optimistic problems, adversarial Search, Search for games, minimax, Alpha - Beta pruning, Heuristic Searchtechniques, HillClimbing, Best-firstsearch, Problem reduction, Constraintsatisfaction, Means Ends Analysis, Iterative deepening Heuristic Search and A*.

UNIT-III LogicandKnowledgeRepresentation 8 Hours

IntroductionofLogic, PropositionalLogic Concepts, Semantic Tableaux and Resolution in FOPL, Logic Programming in Prolog. Production systems and rules for some AI problems: Water Jug Problem, Missionaries-Cannibals Problem, n-Queen problem, monkey banana problem, Travelling Salesman Problem. Knowledge representation, semantic nets, partitionednets, parallelimplementation of semantic nets. Frames, Common Sensereasoning and the maticroleframes.

| 8 H | ours |
|-----|------|
| 8 | H |

Architecture of knowledge-Based System, Rule-based systems, Forward and Backward Chaining, FrameBased systems. Architecture of Expert System, Forward & Backward chaining, Resolution, Probabilisticreasoning, Utilitytheory, Hidden Markov Models (HMM), Bayesian Networks.

| PlanningandUncertainty | 8 Hours |
|------------------------|------------------------|
| | PlanningandUncertainty |

PlanningwithstateSpaceSearch,ConditionalPlanning,Continuousplanning,Multi-AgentPlanning,Formsof learning, inductive learning, Reinforcement Learning, learning decision trees, Neural Net learning andGeneticlearning.ProbabilisticMethods, Bayesian Theory,Dempster ShaferTheory,BayesNetwork. Evolutionary computation: Swarm Intelligence, ant colony optimization Agents, Intelligent Agents, Structure of Intelligent Agents, Virtual Agents, Multi-agent systems.

CaseStudy: HealthCare,ECommerce,SmartCities.

| Course | Course Outcomes: After completion of this course, students will be able to | | |
|--------|---|--------|--|
| 1 | Elaborate historicalperspective of Alandits foundations. | K1 | |
| 2 | Apply principlesofAI toward problem solving and drawing inference thereof. | K1, K4 | |
| 3 | Describe perception, knowledge representation, and different learning techniques. | K2, K3 | |
| 4 | Implement architecture of knowledge-Based System, Rule-based systems, and other expert systems. | K3, K5 | |
| 5 | Apply evolutionary computational algorithms and different search algorithms. | K4, K5 | |

Textbooks:

- 1. StuartRussell, PeterNorvig, "ArtificialIntelligence-AModernApproach", PearsonEducation. FourthEdition2021
- 2. ElaineRichandKevinKnight, "ArtificialIntelligence", McGraw-Hill3rdEdition2010.

ReferenceBooks:

- 1. PatrickHenryWinston, "ArtificialIntelligence", PearsonEducationInc., Thirdedition.
- 2. PythonMachineLearning:LearnPythoninaWeekandMasterIt.AnHands-OnIntroductionto BasedGuidewithPracticalExercises(7DaysCrashCourse,Book2)2020.

ArtificialIntelligenceCoding,aProject-

- 3. NilsJ.Nilsson, "ArtificialIntelligence- ANewSynthesis", HarcourtAsiaPvt. Ltd.
- 4. Alin the Wild: Sustainability in the Age of Artificial Intelligence 2020.
- 5. Knowledge-BasedSystemsTechniquesandApplications(4-VolumeSet).

| Unit1 | https://nptel.ac.in/courses/106/106106198/ |
|-------|--|
| Unit2 | https://nptel.ac.in/courses/111/107/111107137/ |

| Unit3 | https://nptel.ac.in/courses/106/106106202/ |
|-------|--|
| Unit4 | https://nptel.ac.in/courses/106/106106213/ |
| Unit5 | https://nptel.ac.in/courses/106/105/106105152/ |

| | Bachelor of Tech | nology Third Year | |
|--------------------|---|---|---------------|
| Course Code | AEC0651 | L T P | Credit |
| Course Title | Digital Signal Processing Lab | 0 0 2 | 1 |
| Course Objecti | ves: The student will learn about | | |
| 1 | Various matrix operations, different types of signals and its properties used in signal processing. | | |
| 2 | The linear filtering using linear &circular convolution. | | |
| 3 | The concept of frequency domain analysis of discrete the | me system using N point DFT & FFT. | |
| 4 | Performance of FIR and IIR filters using window techn | iques and Butterworth approximation respectively | |
| 5 | Analysis of decimation and interpolation process for m | ulti-rate signal processing. | |
| | | List of Experiments | |
| Sr. No. | Name o | of Experiment | CO |
| 1 | Write a MATLAB program to perform the various | matrix operations: addition, subtraction, multiplication, and | CO1 |
| | inverse of the given sequences as $a = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ | 2] 5] | |
| 2 | | npulse, unit step, ramp, exponential, sinusoidal and cosine for | CO1 |
| | both continuous and discrete time signal using MATLA | | |
| 3 | | lling, time-scaling and time shifting on a given signal $x(n)=$ | CO1 |
| | u(2n-3). | | |
| 4 | Evaluate the DFT and IDFT of a given sequences $x(n) = \{0,1,2,3\}$ and draw the magnitude and phase response of the CO3 | | |
| _ | output sequence using MATLAB. | | |
| 5 | | sequences $x(n) = \{0,1,0,1\} \& h(n) = \{2,3,4\} \text{ using MATLAB}$ | CO2 |
| | for linear filtering applications. | | ~~~ |
| 6 | Evaluate and verify the circular convolution of the given sequences $x(n) = \{1,1,1,1\}$ & $h(n) = \{0,1,0,1\}$ using MATLAB for linear filtering applications. | | CO2 |
| 7 | Analysis of DIT-FFT algorithm for a given sequence $x(n) = \{n+1\}$ for $n = 0, 1, 2, 3$ and draw the frequency spectrum CO3 | | CO3 |
| | of given signals. | | |
| 8 | | tterworth IIR filter for a cut off frequency of 4 KHz also draw | CO4 |
| | the pole-zero diagram, magnitude and phase response u | sing FDA tool. | |
| 9 | Design and analysis of a digital Low Pass and High Pass FIR filter using various rectangular and hamming windows for M=7. | | CO4 |
| | Design and analysis of decimation and interpolation of a given sequence $x(n) = \{1, 2, 2, 3, 2, 1\}$ for decimation | | |
| 10 | factor D=4 and interpolation factor I=3. | | CO5 |
| Course Outcor | nes: After completion of this course students will be a | ble to | |
| CO 1 | Perform various matrix operations, different types of signals and its properties used in signal processing K1, K2 | | K1, K2 |
| CO 2 | Perform the linear filtering using linear &circular conve | olution. | K1, K2 |
| CO 3 | Perform frequency domain analysis of discrete time sys | | K1, K2, K3 |

| CO 4 | Design and evaluate the performance of FIR and IIR filters using window techniques and Butterworth approximation | K1, | K2, |
|------|--|-----|-----|
| | respectively | K3 | |
| CO5 | Design and analyse decimation and interpolation process for multi-rate signal processing. | K1, | K2, |
| | | K3 | |

| Bachelor of Technology Third Year | | | |
|-----------------------------------|--|--|--------|
| Course | AEC0614P | LTP | Credit |
| Code | | | |
| Course | Advanced IoT and Mobile Applications Lab | 0 0 2 | 1 |
| Title | | | |
| Course (| Objectives: Student will learn about | | |
| 1 | The basic fundamentals of Mobile Application Development. | | |
| 2 | The various programs of UI fundamentals, layout and application | | |
| 3 | The implementation of multimedia and animation and connection | on of notification and services. | |
| 4 | The real time applications. | | |
| | Suggested List of Exper | riments | _ |
| Sr. No. | Name of Experiment | | CO |
| 1. | Implementing fundamentals of Mobile Application Developmen | t | CO1 |
| | a. Case study on the architecture of personal smart phone, | | |
| | b. Install the Android Studio 4.2 or higher for Android SDK 11 | | |
| | c. Install developer tools and build a test project to confirm | that those tools are properly installed and | |
| | configured. | | |
| 2. | Implementing UI fundamentals and layouts and develop a progr | am for student's records, Implement | CO1 |
| | followings: - | | |
| | a. Use UI Widgets: 2 TextViews, 2 EditTexts, and one Pus | | |
| | b. One Image button, One toggle button and One table 3x3 | | |
| | Use linear layout, Absolute layout and Relative layout. | | ~ ~ ~ |
| 3. | Implementing UI fundamentals and applications. Develop a pro- | ogram to get students information, Implement | CO2 |
| | followings: - | | |
| | a. To implement checkbox (minimum three options, Ask h | obbies) | |
| | b. Radio button for gender (Male, Female) | | |
| | c. Radio group (minimum three options, Ask skills) | | |
| | d. Progress bar. (Ask Course coverage) | | |
| | e. Use Scroll and list view for checkbox | | |
| | f. Use Image and grid view for radio group.g. Use date and time picker. | | |
| 4. | - | | CO2 |
| 7. | Implementing multimedia and animation. | ' DI 4 4 | CO2 |
| | a. Interfacing Bluetooth connectivity and transmit and receive m | essage using Bluetooth. | |

| | b. Develop program to show human walking animation. | |
|--------|--|-----|
| 5. | Connecting Notifications and services | CO3 |
| | a. Develop a program to send and receive SMS. | |
| | b. Develop a program to send and receive email. | |
| 6. | Develop real-time applications with Android Studio | CO3 |
| | a) Create a native calculator application. | |
| | b) Develop an application that makes use of database. | |
| | c) Develop a native application that uses GPS location information. | |
| | d) Sending sensor data from IoT enabled smart device and publishing on mobile application. | |
| Course | Outcomes: After successful completion of the course students will able to | _ |
| CO 1 | Understand configuration of Android environment and development tools. | K2 |
| CO 2 | Develop rich user interfaces by using layouts, controls, user interface components and animations. | K6 |
| CO 3 | Construct android applications using data bases and connect services. | K6 |
| CO 4 | Implement, test and publish real time Android Applications. | K3 |

| Bachelor of Technology Third Year | | | | |
|-----------------------------------|--|----------------------------|----------|--|
| Course Code | AEC0615P | LTP | Credit | |
| Course Title | Robotics Lab | 0 0 2 | 1 | |
| Course Obj | ectives: Student will learn about | | | |
| CO 1 | The basic features of KUKA sim pro software. | | | |
| CO 2 | The various programs on KUKA Sim Pro software. | | | |
| CO 3 | Basics of the KUKA KR10 robotics arm. | | | |
| CO 4 | Programming & Simulation of different task on KUKA KR10 | | | |
| | Suggested List of Expe | riments | T | |
| Sr. No. | Name of Experiment | | CO | |
| 1. | Study of KUKA sim pro software and its features | | CO1 | |
| 2. | To write a simulation program for welding task. | | CO1 | |
| 3. | To write a simulation program for pick & place task on KUKA | A sim pro software. | CO2 | |
| 4. | Simulation of finger gripper in KUKA sim pro with the help of | a "move tower" project. | CO2 | |
| 5. | Sensing strategy and robot path creation for interrupted welding | ng lines at car underbody. | CO3 | |
| 6. | To study about robotics arm KR 10 and its features. | • | CO3 | |
| 7. | To verify the simulation program for task of pick & place on r | obotic arm KR-10. | CO4 | |
| 8. | To verify the simulation program for welding task on robotic a | arm KR-10. | CO4 | |
| Course Ou | tcomes: After successful completion of the course students wil | l able to | <u>.</u> | |
| CO 1 | Understand the basic features of KUKA sim pro software | | K2 | |
| CO 2 | Understand and simulate the various programs on KUKA Sim | Pro software. | K2, K5 | |
| CO 3 | Learn about the KUKA KR10 robotics arm. | | K1, K2 | |
| CO 4 | Simulate various programs on KUKA KR10 robotics arm. | | K5 | |

| | Bachelor of Technology Th | ird Year | | |
|--------------|---|-------------|-------------------------------|-------------|
| Course Code | AEC0616P | LTP | Credit | |
| Course Title | AI & ML Lab | 0 0 2 | 1 | |
| Course Objec | tives: Student will learn about | | | |
| 6. | Implementation procedures for the machine learning algorithm | S. | | |
| 7. | Design MATLAB/Python programs for various Learning algor | ithms. | | |
| 8. | How to apply appropriate data sets to the Machine Learning alg | | | |
| 9. | Identify and apply Machine Learning algorithms to solve real v | world prob | ems. | |
| | List of Experiment | S | | |
| r. No. | Name of Experiment | | | CO |
| 1 | Implement the S algorithm for finding the most specific hypodata samples. Read the training data from a .csv file. | thesis base | ed on a given set of training | CO1 |
| 2 | For a given set of training data examples stored in a .csv Candidate-Elimination algorithm to output a description of th the training examples. | | | CO1 |
| 3 | Build an Artificial Neural Network by implementing the Ba same using appropriate data sets. | ck propag | ation algorithm and test the | CO2 |
| 4 | Implement the non-parametric Locally Weighted Regression Select appropriate data set for your experiment and draw graph | | in order to fit data points. | CO2 |
| 5 | Write a program to implement the naïve Bayesian classifier for .csv file. Compute the accuracy of the classifier, considering fe | - | _ | CO2 |
| 6 | Assuming a set of documents that need to be classified, use to perform this task. Built-in Java classes/API can be used to wrip precision, and recall for your data set. | | 9 | CO2 |
| 7 | Write a program to construct a Bayesian network consider demonstrate the diagnosis of heart patients using standard I Java/Python ML library classes/API. | | | CO3 |
| 8 | Apply EM algorithm to cluster a set of data stored in a .csv fi using k-Means algorithm. Compare the results of these two alg clustering. You can add Java/Python ML library classes/API in | orithms an | d comment on the quality of | CO4 |
| 9 | Write a program to implement k-Nearest Neighbor algorithm correct and wrong predictions. Java/Python ML library classes | | | CO4 |
| 10 | Write a program to demonstrate the working of the decision appropriate data set for building the decision tree and apply this | on tree ba | sed ID3 algorithm. Use an | CO4 |
| ourse Outco | mes: After successful completion of this course, students will | be able to | | Blooms Leve |

| CO 1 | Explain the implementation procedures for the machine learning algorithms. | K ₃ |
|------|--|---------------------------------|
| CO 2 | Design Python programs for various Learning algorithms. | K ₃ , K ₄ |
| CO 3 | Apply appropriate data sets to the Machine Learning algorithms. | K ₃ , K ₄ |
| CO 4 | Identify and apply Machine Learning algorithms to solve real world problems. | K ₅ |

| B. TECH. THIRD YEAR | | | | | |
|---------------------|--|-------|---------|--|--|
| Course code | ANC0601 | L T | Credits | | |
| | | P | | | |
| Course Title | CONSTITUTION OF INDIA, LAW AND ENGINEERING | 2 0 0 | 2 | | |

Course objective: To acquaint the students with legacies of constitutional development in India and help them to understand the most diversified legal document of India and philosophy behind it.

Pre-requisites: Computer Organization and Architecture

Course Contents / Syllabus

UNIT-I INTRODUCTION AND BASIC INFORMATION ABOUT INDIAN CONSTITUTION

8 Hours

Meaning of the constitution law and constitutionalism, Historical Background of the Constituent Assembly, Government of India Act of 1935 and Indian Independence Act of 1947, Enforcement of the Constitution, Indian Constitution and its Salient Features, The Preamble of the Constitution, Fundamental Rights, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal System, Centre-State Relations, Amendment of the Constitutional Powers and Procedure, The historical perspectives of the constitutional amendments in India, Emergency Provisions: National Emergency, President Rule, Financial Emergency, and Local Self Government – Constitutional Scheme in India.

UNION EXECUTIVE AND STATE EXECUTIVE UNIT-II

8 Hours

Powers of Indian Parliament Functions of Rajya Sabha, Functions of Lok Sabha, Powers and Functions of the President, Comparison of powers of Indian President with the United States, Powers and Functions of Vice-President, Powers and Functions of the Prime Minister, Judiciary – The Independence of the Supreme Court, Appointment of Judges, Judicial Review, Public Interest Litigation, Judicial Activism, LokPal, Lok Ayukta, The Lokpal and Lok ayuktas Act 2013, State Executives – Powers and Functions of the Governor, Powers and Functions of the Chief Minister, Functions of State Cabinet, Functions of State Legislature, Functions of High Court and Subordinate Courts.

INTRODUCTION AND BASIC INFORMATION ABOUT LEGAL SYSTEM UNIT-III

8 Hours

The Legal System: Sources of Law and the Court Structure: Enacted law -Acts of Parliament are of primary legislation, Common Law or Case law, Principles taken from decisions of judges constitute binding legal rules. The Court System in India and Foreign Courtiers (District Court, District Consumer Forum, Tribunals, High Courts, Supreme Court). Arbitration: As an alternative to resolving disputes in the normal courts, parties who are in dispute can agree that this will instead be referred to arbitration. Contract law, Tort, Law at workplace.

8 Hours

Intellectual Property Laws: Introduction, Legal Aspects of Patents, Filing of Patent Applications, Rights from Patents, Infringement of Patents, Copyright and its Ownership, Infringement of Copyright, Civil Remedies for Infringement, Regulation to Information, Introduction, Right to Information Act, 2005, Information Technology Act, 2000, Electronic Governance, Secure Electronic Records and Digital Signatures, Digital Signature Certificates, Cyber Regulations Appellate Tribunal, Offences, Limitations of the Information Technology Act.

UNIT-V BUSINESS ORGANIZATIONS AND E-GOVERNANCE

8 Hours

Sole Traders, Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of Association, Articles of Association, Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up. E-Governance and role of engineers in E-Governance, Need for reformed engineering serving at the Union and State level, Role of I.T. professionals in Judiciary, Problem of Alienation and Secessionism in few states creating hurdles in Industrial development.

COURSE OUTCOMES: After completion of this course students will be able to

| CO 1 | Identify and explore the basic features and modalities about Indian constitution. | K1 |
|------|--|----|
| CO 2 | Differentiate and relate the functioning of Indian parliamentary system at the center and state level. | K2 |
| CO 3 | Differentiate different aspects of Indian Legal System and its related bodies. | K4 |
| CO 4 | Discover and apply different laws and regulations related to engineering practices. | K4 |
| CO 5 | Correlate role of engineers with different organizations and governance models | K4 |

Text Books:

- 1. M Laxmikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill
- 2. Brij Kishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.
- 3. Granville Austin: The Indian Constitution: Cornerstone of a Nation (Classic Reissue), Oxford University Press.

Reference Books:

- 1. Madhav Khosla: The Indian Constitution, Oxford University Press.
- 2. PM Bakshi: The Constitution of India, Latest Edition, Universal Law Publishing.
- 3. V.K. Ahuja: Law Relating to Intellectual Property Rights (2007)

| Bachelor of Technology Third Year | | | | | |
|--|---|-----------------------|--|--|--|
| Course Code | ANC0602 L T P | Credits | | | |
| Course Title | Essence of Indian Traditional Knowledge 2 0 0 | NC | | | |
| Course Objectives: In this course, the student will: | | | | | |
| 1 | Learn the basics of past Indian politics and state polity. | K_1, K_2 | | | |
| 2 | Aware of the Vedic system | K_1 | | | |
| 3 | Understand the different religions and religious movements in India. | K2 | | | |
| 4 | Learn the basic knowledge about the ancient history of Indian agriculture, science & technology, and ayurveda | K ₁ | | | |
| 5 | Understand Indian dances, fairs & festivals, and cinema. | K ₂ | | | |
| Pro-requisites: Po | alitical science | | | | |

Pre-requisites: Political science

Course Contents / Syllabus

UNIT-I Society State and Polity in India 4 hours

State in Ancient India: Evolutionary Theory, Force Theory, Mystical Theory Contract Theory, Stages of State Formation in Ancient India, Kingship, Council of Ministers Administration Political Ideals in Ancient India, Conditions of the Welfare of Societies, The Seven Limbs of the State, Society in Ancient India, Purusārtha, Āshrama or the Stages of Life, Marriage, Understanding Gender as a social category, The representation of Women in Historical traditions, Challenges faced by Women.

UNIT-II Indian Literature, Culture, Tradition, and Practices

6 hours

Evolution of script and languages in India: Harappan Script and Brahmi Script. The Vedas, the

Upanishads, the Ramayana and the Mahabharata, Puranas, Buddhist And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sanskrit Authors, Telugu Literature, Kannada Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persian And Urdu, Hindi Literature

UNIT-III Indian Religion, Philosophy, and Practices

4 hours

Pre-Vedic and Vedic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophical Doctrines, Other Heterodox Sects, Bhakti Movement,

Sufi movement, Socio religious reform movement of 19th century, Modern religious practices.

UNIT-IV Science, Management and Indian Knowledge System

4 hours

Astronomy in India, Chemistry in India, Mathematics in India, Physics in India, Agriculture in India, Medicine in India, Metallurgy in India, Geography, Biology, Harappan Technologies, Water Management in India, Textile Technology in India, Writing Technology in India Pyrotechnics in India Trade in Ancient India/, India's Dominance up to Pre-colonial Times.

UNIT-V Cultural Heritage and Performing Arts

6 hours

Indian Architect, Engineering and Architecture in Ancient India, Sculptures, Pottery, Painting, Indian Handicrafts, UNESCO'S List of World Heritage Sites in India, Seals, coins, Puppetry, Dance, Music, Theatre, Drama, Martial Arts Traditions, Fairs and Festivals, UNESCO'S List of

| Intangible Culture | Heritage, Calendars, Current developments in Arts and Cultural, Indian's Cultural Contribution to the World, Ir | ndian Cinema. |
|--------------------|---|---------------|
| Course outcome: | After completion of this course students will be able to | |
| CO 1 | Understand the basics of past Indian politics and state polity. | K2 |
| CO 2 | Understand the Vedas, Upanishads, languages & literature of Indian society. | K2 |
| CO 3 | Know the different religions and religious movements in India. | K4 |
| CO 4 | Identify and explore the basic knowledge about the ancient history of Indian agriculture, science & technology, and ayurveda. | K4 |
| CO 5 | Identify Indian dances, fairs & festivals, and cinema. | K1 |
| Text books | | |
| 4. S. Baliyan, | Indian Art and Culture, Oxford University Press, India | |
| 5. Nitin Singh | ania, Indian Art and Culture: for civil services and other competitive Examinations,3rd Edition, Mc Graw Hill | |
| 6. Swami Jitat | manand, Modern Physics and Vedant, Bharatiya Vidya Bhavan | |
| Reference Books | | |
| 4. Romila Tha | par, Readings In Early Indian History Oxford University Press, India | |
| 5. Basham, A. | L., The Wonder that was India (34th impression), New Delhi, Rupa & co | |
| 6. Sharma, R.S | S., Aspects of Political Ideas and Institutions in Ancient India (fourth edition), Delhi, Motilal Banarsidass | |